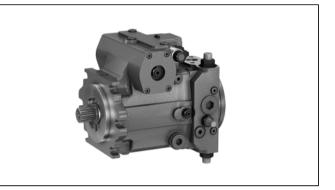


Axial piston variable pump AA4VG Series 32

Americas

RE-A 92003

Edition: 06.2018 Replaces: 04.2016



- ► High-pressure pump for applications in a closed circuit
- ▶ Size 28 to 125
- ► Nominal pressure 5800 psi (400 bar)
- ► Maximum pressure 6500 psi (450 bar)
- Closed circuit

Features

- Integrated auxiliary pump for boost and pilot oil supply
- ► Flow direction changes smoothly when the swashplate is moved through the neutral position
- ► High-pressure relief valves with integrated boost function
- ▶ With adjustable pressure cut-off as standard
- ► Boost-pressure relief valve
- ► Through drive for mounting of further pumps up to same nominal size
- ► Large variety of controls
- Swashplate design

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Type code

01	. 02	03	04	05	06	07	08	09		10	11		12	13	14	15	16	17	18	19	20	21	22
AA4	\$V G			D					/	32		_	N										
Axial	piston	unit																					
01	Swash	plate d	esign,	, varia	ıble, n	ominal	press	ure 58	300 ps	i (400	bar),	maxin	num p	ressu	re 650) psi (4	150 ba	ar)					AA4\
Opera	ating m	ode																					
02	Pump,	closed	circu	it																			G
Size ((NG)																						
03	Geome	etric di	splace	ment	, see '	"Techn	ical da	ta" or	page	8					in³/re	ev.	1.71	2.44	3.42	4.33	5.49	7.63	
	cm³/rev. 28 40 56 71 90 12											125											
Conti	rol devi	ce															28	40	56	71	90	125	,
04	Without control module											•	NV										
	Proportional control, hydraulic Pilot-pressure related <i>p</i> = 87 to 260 psi (6 to 18 bar) o o • • •											•	HD3										
						M	echan	ical se	ervo								•	•	•	•	•	•	нw
	Propor	rtional	contro	ol, ele	ctric										<i>U</i> = 1	2 V	•	•	•	•	•	•	EP3
													•	EP4									
	Two-po	Two-point control, electric $U = 12 \ \lor \bullet \bullet \bullet \bullet \bullet \bullet$											•	EZ1									
	<i>U</i> = 24 ∨ • • • • • •											•	EZ2										
	Automatic control, speed related $U = 12 \text{ V}$ • • • • •											•	DA1										
													•	DA2									
												•	DG										
	Electri two pr				•	ed,									U = 1	-	•	•	•	•	-	_	ET5
	two pi	essure	reduc	Jilig v	aives										U = 2	4 V	•	•	•	•	_	-	ЕТ6
Press	ure cut																						
05	Pressu	re cut-	off (st	andaı	rd)																		D
Neuti	ral posi	tion sv	vitch																				
06	Withou	ut neut	ral pos	sition	switc	h (with	out co	ode)						,		,						•	
	Neutra	ıl posit	ion sw	/itch ((for H	W cont	rol onl	y)														•	L
Mech	anical s	stroke	limite	r																			
07	Withou	ut mecl	nanica	l stro	ke lim	iter (w	ithout	code))													•	
	Mecha	nical s	troke l	limite	r, exte	rnally	adjusta	able														•	М
Strok	ing cha	mber ı	oressu	ıre po	ort												28	40	56	71	90	125	
08	Withou	ut strok	ing ch	nambe	er pre	ssure p	ort X 3	, X ₄ (\	withou	ıt code	e)						•	•	•	•	•	•	
	Strokir	ng char	nber p	oressu	ıre po	rt X 3,)	(₄										0	0	•	•	•	•	Т
DA co	ontrol v	alve														NV	HD	HW	DG	DA	ΕP	ΕZ	
09	Withou	ıt DA c	ontrol	valve	;											•	•	•	•	-	•	•	1
	DA cor	ntrol va	lve, fix	xed se	etting											-	•	•	•	•	•	_	2
	DA control valve, mechanically adjustable with position direction of actuation, clockwise - • • • •								-	3R													
	lever direction of actuation, • • • • • •							_	3L														
	DA cor	ntrol va	lve, fix	xed se	etting,	ports	for pil	ot con	trol d	evice						_	0	0	-	0	0	-	7
	DA cor brake i				_		th bra	ke flui	d	ba	ased o	on min	eral o	il		-	-	-	-	•	-	-	8
• =	Availa	ble	0 :	= Or	n req	uest	_ :	= No	t avai	ilable			=	Prefe	erred	orogra	am						

01 AA 4		03 T	04	05 D	06	07	08 	09 	,	10 32	11	Ι_	12 N	13	14 	15	16 	17 	18 	19	20	21	T 22
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erie 10	Series 3	o indo	v 1																				32
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	tion of r			_																			_
11	Viewed	on dri	ve sha	ft												kwise				-			F
															cour	iter-clo	ckwise						L
Seali	ng matei	rial																					
12	NBR (n	BR (nitrile rubber), shaft seal in FKM (fluoroelastomer)												I									
Drive	shaft	shaft 28 40 56 71 90 125																					
13	Splined	lined shaft for single pump															•	•	•	•	•	•	5
	ANSI BS	NSI B92.1a for combination pump								mp – 1	Lst pui	mp					_1)	_1)	•	•	_1)	•	ī
		only for combination pump – 2nd pump									np				-	•	-	-	•	-	ī		
Mour	nting flar	z flange											28	40	56	71	90	125					
14	SAE J74									2-h	ole					T.	•	•	<u>-</u>	-	<u>-</u>	7	
		2+4-hole										+-	-	† <u>-</u>	•	•	•						
Mark	ing port										,						28	40	56	71	90	125	
15	SAE working port A and B , top and bottom Suction port S bottom										40	30	•	•	125	5							
	SAE wo												ort S				 	0	•	_	-	0	5
	SAE wo											Suction port S bottom					•	-	† <u>-</u>	-	-	-	Ė
	SAE wo										Suction port S bottom						 	<u> </u>	† <u>-</u>	•	<u> </u>	 	6
	SAE wo							2)			Suction port S top						T -	 	† -	-	-	0	6
Roos	t pump										odollon port o top							1	1				
16	Without	t integ	rated b	oost	nump						without through drive												
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	Integrat	ted boo	ost pui	mp									witho		ough (drive							F
																		40				405	
	Withou		ah driv		rcions	Nanc	4 F (p.	16)	only								28	40	56	71	90	125	0
17	Flange			ve, ve	SIONS		ub for			f+							•	•	•	•	•	•	<u> </u>
	82-2 (A		44 '				8 in 9								-		•						0
																		H				0	
	1012(101-2 (B) 7/8 in 13T 16/32DP ⁵⁾ 1 in 15T 16/32DP ⁵⁾												•	•	•	•	•	•	0			
	127-2 (127-2 (C) ⁶⁾ 1 1/4 in 14T 12/24DP ⁵⁾)P ⁵⁾						-	-	•	•	•	•	0			
								13T 8							-		-	 _	+-	<u> </u>	 -	•	6
	152-2/4	l (D)																					

¹⁾ Standard for combination pump – 1st pump: Shaft S

²⁾ Only possible without attachment filter

³⁾ Specifications for version with integrated boost pump, please contact us for version without boost pump

^{4) 2 = 2-}hole; 4 = 4-hole

⁵⁾ Hub for splined shaft to ANSI B92.1a

⁶⁾ NG90 to 125 with additional 4-hole-flange (127-4)

4 AA4VG Series 32 | Axial piston variable pump Type code 05 16 18 AA4V G D 32 High-pressure relief valve Setting range Δp 28 40 56 71 90 125 18 High pressure relief valve, pilot operated 1450 to 6100 psi with bypass (100 to 420 bar) High-pressure relief valve, direct operated, 3600 to 6100 psi without bypass 3 • • • fixed setting (250 to 420 bar) with bypass 5 • without bypass 4 1450 to 3600 bar (100 to 250 bar) with bypass _ _ 6 • • • Filtration boost circuit/external boost pressure supply 28 40 56 71 90 125 19 | Filtration in the boost pump suction line • S • • • • • Filtration in the boost pump pressure line D Ports for external boost circuit filtration (Fe and Fa) Mounted cold start valve and ports for external boost circuit filtration Κ Attachment filter with cold start valve F _ Attachment filter with cold start valve and visual contamination indicator Attachment filter with cold start valve and electric contamination indicator _ • • • В External boost pressure supply (version without integrated boost pump - N00, K...) • Ε • • • • Swivel angle sensor 28 40 56 71 90 125 Without swivel angle sensor (without code) • Electric swivel angle sensor⁷⁾ 0 Connector for solenoids8) Without connector (without code), only for purely hydraulic control DEUTSCH molded connector, 2-pin without suppressor diode with suppressor diode (only for EZ and DA) Q Standard / special version 22 Standard version without code -K combined with attachment part or attachment pump -s Special version combined with attachment part or attachment pump -SK

= Preferred program

Notice

Available

- Note the project planning notes on page 68.
- ► In addition to the type code, please specify the relevant technical data when placing your order.

o = On request

- = Not available

⁷⁾ Please contact us if the swivel angle sensor is used for control

⁸⁾ Connectors for other electric components may deviate

Hydraulic fluids

The AA4VG variable pump is designed for operation with HLP mineral oil according to DIN 51524.

Application instructions and requirements for hydraulic fluids should be taken from the following data sheets before the start of project planning:

- 90220: Hydraulic fluids based on mineral oils and related hydrocarbons
- ▶ 90221: Environmentally acceptable hydraulic fluids
- ▶ 90222: Fire-resistant, water-free hydraulic fluids (HFDR/HFDU)
- ▶ 90225: Axial piston units for operation with water-free and water-containing fire-resistant hydraulic fluids (HFDR, HFDU, HFAE, HFAS, HFB, HFC).

Notes on selection of hydraulic fluid

The hydraulic fluid should be selected such that the operating viscosity in the operating temperature range is within the optimum range (v_{opt} see selection diagram).

Notice

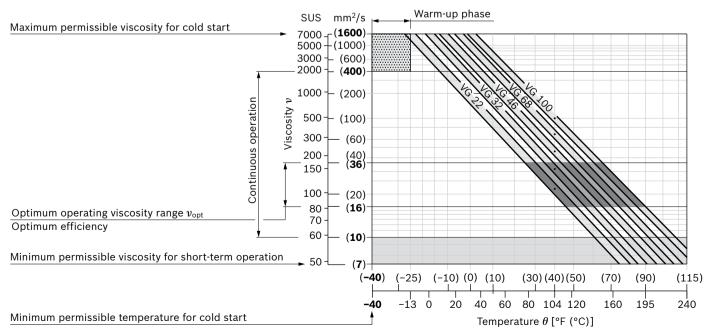
At no point of the component may the temperature be higher than 240 °F (115 °C). The temperature difference specified in the table is to be taken into account when determining the viscosity in the bearing.

Please contact us if the above conditions cannot be met due to extreme operating parameters.

Viscosity and temperature of hydraulic fluids

	Viscosity [SUS (mm ² /s)]	Temperature	Comment
Cold start	$v_{\text{max}} \le 7400 \ (1600)$	θ _{St} ≥ -40 °F (-40 °C)	$t \le 3$ min, $n \le 1000$ rpm, without load $p \le 725$ psi (50 bar)
Permissible temper	Permissible temperature difference		between axial piston unit and hydraulic fluid in the system
Warm-up phase	ν = 7400 to 1850 (1600 to 400)	θ = -40 °F to -13 °F (-40 °C to -25 °C)	at $p \le 0.7 \times p_{\text{nom}}$, $n \le 0.5 \times n_{\text{nom}}$ and $t \le 15$ min
Continuous operation	ν = 1850 to 60 (400 to 10)		this corresponds, for VG 46 for example, to a temperature range of +41 °F (5 °C) to + 185 °F (85 °C) (see selection diagram)
		θ = -13 °F to +230 °F (-25 °C to +110 °C)	measured at port T Observe the permissible temperature range of the shaft seal (ΔT = approx. 9 °F (5 K) between bearing/shaft seal and port T)
	$v_{\rm opt}$ = 170 to 82 (36 to 16)		Range of optimum operating viscosity and efficiency
Short-term operation	$v_{\text{min}} \ge 49 (7)$		$t < 3 \text{ min}, p < 0.3 \times p_{\text{nom}}$

▼ Selection diagram



Filtration of the hydraulic fluid

Finer filtration improves the cleanliness level of the hydraulic fluid, which increases the service life of the axial piston unit.

A cleanliness level of at least 20/18/15 is to be maintained according to ISO 4406.

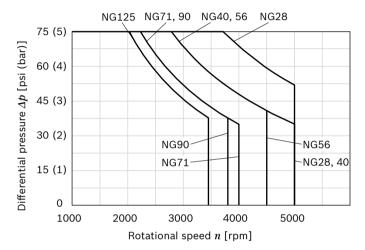
Depending on the system and the application, for the AA4VG we recommend: Filter elements $\beta_{20} \ge 100$. At very high hydraulic fluid temperatures (194 °F (90 °C) to maximum 230 °F (110 °C), measured at port **T**), a cleanliness level of at least 19/17/14 according to ISO 4406 is necessary.

Shaft seal

Permissible pressure loading

The service life of the shaft seal is influenced by the rotational speed of the axial piston unit and the leakage pressure in the housing (case pressure). Momentary (t < 0.1 s) pressure peaks of up to 145 psi (10 bar) are allowed. The service life of the shaft seal decreases with increasing frequency of pressure peaks and increasing mean differential pressure.

The case pressure must be higher than the ambient pressure.

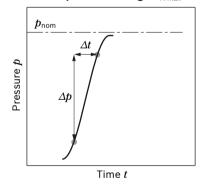


The FKM shaft seal ring may be used for leakage temperatures from -13 °F to +239 °F (-25 °C to +115 °C). For application cases below -13 °F (-25 °C), an NBR shaft seal is required (permissible temperature range: -40 °F to +194 °F (-40 °C to +90 °C)).

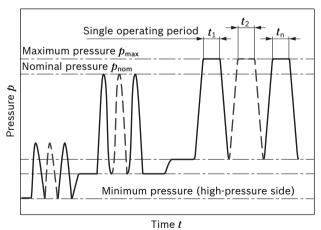
Working pressure range

Pressure at working port A or B		Definition
Nominal pressure p_{nom}	5800 psi (400 bar)	The nominal pressure corresponds to the maximum design pressure.
Maximum pressure $p_{\sf max}$	6500 psi (450 bar)	The maximum pressure corresponds to the maximum working pressure within
Single operating period	10 s	the single operating period. The sum of the single operating periods must not
Total operating period	300 h	exceed the total operating period.
Minimum pressure (high-pressure side)	365 psi (25 bar)	Minimum pressure at the high-pressure side (A or B) which is required to prevent damage to the axial piston unit.
Minimum pressure (low-pressure side)	145 psi (10 bar) above case pressure	Minimum pressure at the low-pressure side ($\bf A$ or $\bf B$) which is required to prevent damage to the axial piston unit.
Rate of pressure change $R_{\rm A\ max}$	130000 psi/s (9000 bar/s)	Maximum permissible rate of pressure build-up and reduction during a pressure change across the entire pressure range.
Boost pump		
Nominal pressure $p_{\sf Sp\ nom}$	365 psi (25 bar)	
Maximum pressure $p_{\sf Sp\ max}$	580 psi (40 bar)	
Pressure at suction port S (inlet)		
Continuous $p_{S \text{ min}}$ $(v \le 140 \text{ SUS})$ $(v \le 30 \text{ mm}^2/\text{s})$	≥ 12 psi absolute (≥ 0.8 bar absolute)	
Momentary, during cold start (t < 3 min)	≥ 7.5 psi (0.5 bar) absolute	
Maximum pressure $p_{\text{S max}}$	≤ 75 psi (5 bar) absolute	
Control pressure		
Minimum control pressure $p_{ m St\;min}$ Controls EP, HD, HW	290 psi (20 bar) above	To ensure the function of the control, a minimum control pressure $p_{\rm St\ min}$ at n = 2000 rpm is necessary depending on the rotational speed and working
	case pressure	pressure
Controls DA, DG, EZ, ET	365 psi (25 bar) above case pressure	

▼ Rate of pressure change R_{A max}



▼ Pressure definition



Total operating period = $t_1 + t_2 + ... + t_n$

Notice

Working pressure range valid when using hydraulic fluids based on mineral oils. Please contact us for values for other hydraulic fluids.

Technical data

$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Size				NG	28	40	56	71	90	125
$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	Displacement,	geometric, per revolution	'	$V_{g\;max}$	in ³	1.71	2.44	3.42	4.33	5.49	7.63
Redational speed		variable pump				28	40	56	71	90	125
Productional Speed Produ		boost pump (at $p = 2$	290 psi (20 bar))	V_{gSp}	in ³	0.37	0.52	0.71	1.20	1.20	1.73
Sepect Filmited, maximum Minited, maximum					cm ³	6.1	8.6	11.6	19.6	19.6	28.3
$\ln (1 + in) (1 + i$	Rotational	maximum at V_{gmax}		n_{nom}	rpm	4250	4000	3600	3300	3050	2850
Flow at n_{nom} and $V_{\text{g max}}$ and $V_{$	speed ¹⁾	limited, maximum ²⁾		n_{max1}	rpm	4500	4200	3900	3600	3300	3250
Flow $\frac{1}{1}$ at n_{nom} and V_{gmax} and $\frac{1}{1}$ at n_{nom} , v_{gmax} and n_{nom} , v_{gmax}		intermittent, maximu	ım ³⁾	n_{max2}	rpm	5000	5000	4500	4100	3800	3450
Power 4) at n_{nom} , $V_{\text{g max}}$ and O at n_{pom} , $V_{\text{g max}}$ and O at n_{pom} , $V_{\text{g max}}$ and O at n_{pom} , $V_{\text{g max}}$ and O at $N_{\text{g max}}$ and O at $N_{g max$		minimum		n_{min}	rpm	500	500	500	500	500	500
Power $^{4)}$ at n_{nom} , $V_{\text{g max}}$ and $\frac{Ap}{a}$ = 5800 psi P hp 106 143 180 209 245 319 $Ap = 400 \text{bar}$ P kW 79 107 134 156 183 238 P Torque $^{4)}$ at $V_{\text{g max}}$ and $P_{\text{g max}}$ and $P_{g $	Flow	at n_{nom} and V_{gmax}		q_{v}	gpm	31.4	42.3	53.4	61.8	72.6	94
Torque4) at $V_{\rm gmax}$ and $Ap = 400 {\rm bar}$ P kW 79 107 134 156 183 238 587 $Ap = 400 {\rm bar}$ P kW 79 107 134 156 183 238 587 $Ap = 400 {\rm bar}$ P kW 79 107 134 156 183 238 587 $Ap = 400 {\rm bar}$ P kW 79 108 255 357 452 573 796 $Ap = 400 {\rm bar}$ P kW 79 108 255 357 452 573 796 $Ap = 400 {\rm bar}$ P kW 79 108 255 357 452 573 796 $Ap = 400 {\rm bar}$ P kW 45 66 83 105 147 P kW 45 64 89 113 143 199 P kW 79 109 P kW 79 109 P kW 79 109 P					l/min	119	160	202	234	275	356
Torque ⁴⁾ at $V_{g max}$ and $Ap = 5800 psi T$ lb-ft 131 188 263 333 423 587 452 573 796 459 1450 psi T lb-ft 33 47 66 83 105 147 459 100 bar T Nm 45 64 89 113 143 199 190	Power ⁴⁾	at n_{nom},V_{gmax} and	$\Delta p = 5800 \text{ psi}$	P	hp	106	143	180	209	245	319
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			Δp = 400 bar	P	kW	79	107	134	156	183	238
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Torque ⁴⁾	at V_{gmax} and	$\Delta p = 5800 \text{ psi}$	T	lb-ft	131	188	263	333	423	587
Rotary stiffness of drive shaft S C S			Δp = 400 bar	T	Nm	178	255	357	452	573	796
Rotary stiffness of drive shaft S c			$\Delta p = 1450 \text{ psi}$	T	lb-ft	33	47	66	83	105	147
Name			Δp = 100 bar	T	Nm	45	64	89	113	143	199
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Rotary stiffness	s of drive shaft	S	c	lb-ft/rad	23159	50892	59595	72871	116609	161010
$\frac{\text{kNm/rad}}{\text{U}} = \frac{\text{kNm/rad}}{\text{U}} = \frac{-}{37468} = \frac{95}{120.9} = \frac{252.1}{20.9}$ $\frac{\text{U}}{\text{V}} = \frac{\text{Ib-ft/rad}}{\text{kNm/rad}} = \frac{37468}{50.8} = \frac{-}{107.6} = \frac{107.6}{20.9}$ $\frac{\text{Moment of inertia for rotary group}}{\text{Maximum angular acceleration}} = \frac{J_{\text{TW}}}{\text{W}} = \frac{\text{Ibs-ft}^2}{\text{kgm}^2} = \frac{0.0522}{0.0022} = \frac{0.0902}{0.0038} = \frac{0.2302}{0.0066} = \frac{0.3362}{0.0097} = \frac{0.5505}{0.0149} = \frac{0.0232}{0.0038}$ $\frac{\text{Maximum angular acceleration}}{\text{Case volume}} = \frac{a}{10.99} = \frac{0.24}{0.29} = \frac{0.40}{0.40} = \frac{0.34}{0.40} = \frac{0.40}{0.55}$ $\frac{\text{Weight (without through drive) approx.}}{\text{Weight (without through drive) approx.}} = \frac{a}{10.99} = \frac{1.1}{1.1} = \frac{1.5}{1.5} = \frac{1.3}{1.3} = \frac{1.5}{1.5} = \frac{2.1}{1.6}$					kNm/rad	31.4	69	80.8	98.8	158.1	218.3
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			T	c	lb-ft/rad	_	-	70068	89171	-	185939
$\frac{\text{kNm/rad}}{\text{Moment of inertia for rotary group}} \qquad \frac{\text{kNm/rad}}{\text{J}_{\text{TW}}} = \frac{50.8}{\text{lbs-ft}^2} = \frac{50.8}{0.0522} = \frac{-}{0.0902} = \frac{107.6}{0.2302} = \frac{-}{0.3536} = \frac{0.5505}{0.5505}$ $\frac{\text{kgm}^2}{\text{kgm}^2} = \frac{0.0022}{0.0038} = \frac{0.0066}{0.0097} = \frac{0.0149}{0.0149} = \frac{0.0232}{0.0038}$ $\frac{\text{Maximum angular acceleration}}{\text{Case volume}} = \frac{V}{\text{gal}} = \frac{0.24}{0.29} = \frac{0.40}{0.40} = \frac{0.34}{0.34} = \frac{0.40}{0.55}$ $\frac{1}{\text{l}} = \frac{0.9}{0.9} = \frac{1.1}{1.1} = \frac{1.5}{1.5} = \frac{1.3}{1.5} = \frac{1.76}{1.5}$ $\frac{1.5}{1.5} = \frac{1.76}{0.9}$ Weight (without through drive) approx. $m = \frac{105}{0.09} = \frac{64}{0.0902} = \frac{84}{0.0902} = \frac{107.6}{0.0902} = \frac{-}{0.0032} = \frac{107.6}{0.0902} = \frac{-}{0.0032}$					kNm/rad	_	_	95	120.9	_	252.1
Moment of inertia for rotary group J_{TW} $\begin{array}{c ccccccccccccccccccccccccccccccccccc$			U	c	lb-ft/rad	_	37468	-	_	79362	-
kgm² 0.0022 0.0038 0.0066 0.0097 0.0149 0.0232 Maximum angular acceleration ⁵) α rad/s² 38000 30000 24000 21000 18000 14000 Case volume V gal 0.24 0.29 0.40 0.34 0.40 0.55 I 0.9 1.1 1.5 1.3 1.5 2.1 Weight (without through drive) approx. m lbs 64 68 84 110 132 176					kNm/rad	_	50.8	_	_	107.6	_
Maximum angular acceleration 5) α rad/s² 38000 30000 24000 21000 18000 14000 Case volume V gal 0.24 0.29 0.40 0.34 0.40 0.55 I 0.9 1.1 1.5 1.3 1.5 2.1 Weight (without through drive) approx. m lbs 64 68 84 110 132 176	Moment of iner	rtia for rotary group		J_{TW}	lbs-ft ²	0.0522	0.0902	0.1566	0.2302	0.3536	0.5505
V gal 0.24 0.29 0.40 0.34 0.40 0.55 I 0.9 1.1 1.5 1.3 1.5 2.1 Weight (without through drive) approx. m lbs 64 68 84 110 132 176					kgm²	0.0022	0.0038	0.0066	0.0097	0.0149	0.0232
1 0.9 1.1 1.5 1.3 1.5 2.1	Maximum angu	lar acceleration ⁵⁾		α	rad/s²	38000	30000	24000	21000	18000	14000
Weight (without through drive) approx. m lbs 64 68 84 110 132 176	Case volume			\overline{V}	gal	0.24	0.29	0.40	0.34	0.40	0.55
					1	0.9	1.1	1.5	1.3	1.5	2.1
kg 29 31 38 50 60 80	Weight (withou	it through drive) approx.		m	lbs	64	68	84	110	132	176
					kg	29	31	38	50	60	80

Notice

- ► Theoretical values, without efficiency and tolerances; values rounded
- ▶ Operation above the maximum values or below the minimum values may result in a loss of function, a reduced service life or in the destruction of the axial piston unit. Bosch Rexroth recommend testing the loads by means of experiment or calculation / simulation and comparison with the permissible values.
- 1) The values are applicable:
 - for the optimum viscosity range from $v_{\rm opt}$ = 170 to 82 SUS (36 to 16 mm²/s)
 - for hydraulic fluid based on mineral oils (for HF hydraulic fluids, observe the technical data in 90225)
- ₂₎ Valid at half corner power (e.g. at $V_{\rm g\;max}$ and $p_{\rm N}/2$)
- 3) Valid at Δp = 1000 to 2200 psi (70 to 150 bar) or Δp < 4350 psi (300 bar) and t < 0.1 s
- 4) Without boost pump

Determining the operating characteristics

Flow
$$q_{\rm v} = \frac{V_{\rm g} \times n \times \eta_{\rm v}}{231}$$
 [gpm] $\left(\frac{V_{\rm g} \times n \times \eta_{\rm v}}{1000}\right)$ [l/min]

Torque $T = \frac{V_{\rm g} \times \Delta p}{24 \times n \times \eta_{\rm hm}}$ [lb-ft] $\left(\frac{V_{\rm g} \times \Delta p}{24 \times n \times \eta_{\rm hm}}\right)$ [Nm]

Power $P = \frac{2 \pi \times T \times n}{33000} = \frac{q_{\rm v} \times \Delta p}{1714 \times n_{\rm t}}$ [HP] $\left(\frac{2 \pi \times T \times n}{60000} = \frac{q_{\rm v} \times \Delta p \times \eta_{\rm t}}{600}\right)$ [kW]

Key

 $V_{\rm g}$ Displacement per revolution [in³ (cm³⁾]

 Δp Differential pressure [psi (bar)]

n Rotational speed [rpm]

 η_{v} Volumetric efficiency

 $\eta_{\rm mh}$ Hydraulic-mechanical efficiency

 η_{t} Total efficiency $(\eta_{t} = \eta_{v} \times \eta_{mh})$

5) The data are valid for values between the minimum required and maximum permissible rotational speed.

Valid for external excitation (e.g. diesel engine 2 to 8 times rotary frequency, cardan shaft twice the rotary frequency).

The limit value is only valid for a single pump.

The load capacity of the connecting parts must be considered.

Permissible radial and axial forces on the drive shaft

▼ Splined shaft ANSI B92.1a

Size		NG		28	40	40	56	56	71
Drive shaft			in	1	1	1 1/4	1 1/4	1 3/8	1 1/4
Maximum radial	⊥ F I	$F_{q\;max}$	lbf	671	958	766	1073	975	1360
force at distance a	Fq		N	2983	4261	3409	4772	4338	6050
(from shaft collar)	a	a	in	0.75	0.75	0.94	0.94	0.94	0.94
	4 [₩] +		mm	19	19	24	24	24	24
Maximum		+ F _{ax max}	lbf	350	477	477	654	654	954
axial force	_E +→		N	1557	2120	2120	2910	2910	4242
	Fax_ ←	- F _{ax max}	lbf	94	198	198	355	355	620
			N	417	880	880	1490	1490	2758
Size		NG		71	90	90	125	125	
Size Drive shaft		NG	in	71 1 3/8	90 1 1/4	90	125 1 3/4	125	
	ıE İ	NG F _{q max}	in Ibf						
Drive shaft Maximum radial force at distance a				1 3/8	1 1/4	1 3/4	1 3/4	2	
Drive shaft Maximum radial	₩ Fq		lbf	1 3/8 1236	1 1/4 1724	1 3/4 1232	1 3/4 1711	2 1497	
Drive shaft Maximum radial force at distance a	Fq	$F_{q\;max}$	lbf N	1 3/8 1236 5500	1 1/4 1724 7670	1 3/4 1232 5478	1 3/4 1711 7609	2 1497 6658	
Drive shaft Maximum radial force at distance a	F _q	$F_{q\;max}$	lbf N in	1 3/8 1236 5500 0.94	1 1/4 1724 7670 0.94	1 3/4 1232 5478 1.32	1 3/4 1711 7609 1.32	2 1497 6658 1.57	
Drive shaft Maximum radial force at distance a (from shaft collar)	F +	F _{q max}	Ibf N in mm	1 3/8 1236 5500 0.94 24	1 1/4 1724 7670 0.94	1 3/4 1232 5478 1.32 33.5	1 3/4 1711 7609 1.32 33.5	2 1497 6658 1.57 40	
Drive shaft Maximum radial force at distance a (from shaft collar) Maximum	F _{ax} +	F _{q max}	Ibf N in mm Ibf	1 3/8 1236 5500 0.94 24 954	1 1/4 1724 7670 0.94 24 973	1 3/4 1232 5478 1.32 33.5 973	1 3/4 1711 7609 1.32 33.5 1361	2 1497 6658 1.57 40 1361	

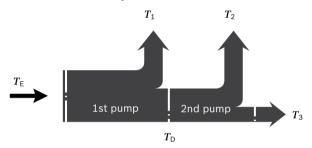
Notice

- ► The axial and radial forces generally influence the service life of the bearings.
- ► Special requirements apply in the case of belt drive and cardan shaft. Please contact us.

Permissible input and through-drive torques

Size		NG		28	40	56	71	90	125
Torque at V_{gmax} and $\ \angle$	$\Delta p = 5800 \text{ psi}^{1)}$	T	lb-ft	131	188	263	333	423	587
	1 p = 400 bar ¹⁾	T	Nm	178	255	357	452	573	796
Maximum input torque	S	$T_{E\;max}$	lb-ft	232	444	444	444	1210	1210
at drive shaft ²⁾	43		Nm	314	602	602	602	1640	1640
ANSI B92.1a (SAE J744	1)		in	1	1 1/4	1 1/4	1 1/4	1 3/4	1 3/4
	T	$T_{E\;max}$	lb-ft	_	_	715	715	_	1969
			Nm	_	_	970	970	_	2670
			in	_	_	1 3/8	1 3/8	_	2
	U ₃₎	$T_{E\;max}$	lb-ft	_	232	_	_	444	_
			Nm	_	314	_	_	602	_
			in	_	1	_	_	1 1/4	_
Maximum through-drive	e torque ⁴⁾	$T_{D\;max}$	lb-ft	170	232	384	487	606	819
			Nm	231	314	521	660	822	1110

Distribution of torques



Torque at 1st pump	T_1		
Torque at 2nd pump	T_2		
Torque at 3rd pump	T_3		
Input torque	T_E	=	$T_1 + T_2 + T_3$
	T_E	<	T _{E max}
Through-drive torque	T_D	=	$T_2 + T_3$
	T_D	<	T_{Dmax}

¹⁾ Efficiency not considered

²⁾ For drive shafts free of radial force

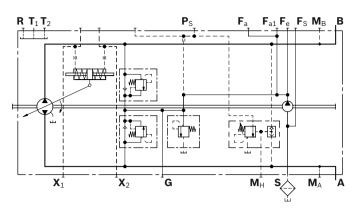
³⁾ Shaft "U" is only permitted as drive shaft on the 2nd pump on a combination pump of the same size.

⁴⁾ Note maximum input torque for shaft S!

NV - Version without control module

The mounting surface for the control module is machined and sealed with the standard seal for control modules and a cover plate. This version is ready for retrofitting to control modules (HD, HW, EP, EZ). When used directly for "DA" control and in combinations with "DA" control, the appropriate adjustments must be made to the spring assembly of the adjustment cylinder and control plate.

▼ Standard version¹⁾



DG - Hydraulic control, direct operated

With the direct operated hydraulic control (DG), the output flow of the pump is controlled by a hydraulic control pressure, applied directly to the stroking piston through either port X_1 or X_2 .

Flow direction is determined by which control pressure port is pressurized (refer to table below).

Pump displacement is infinitely variable and proportional to the applied control pressure, but is also influenced by system pressure and pump drive speed.

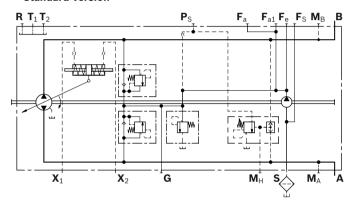
In order to use the optional built-in pressure cut-off, port \mathbf{P}_{S} must be used as the control pressure source for the selected control module.

See page 54 for a functional description of the pressure cut-off.

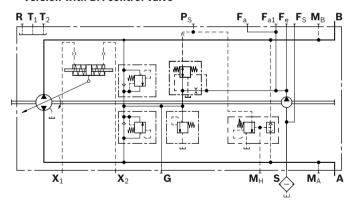
Maximum permissible control pressure: 580 psi (40 bar) Use of the DG control requires a review of the engine and vehicle parameters to ensure that the pump is set up correctly. We recommend that all DG applications be reviewed by a Bosch Rexroth application engineer.

If the pump is also equipped with a DA control valve (see page 19), automotive operation is possible for travel drives.

▼ Standard version¹⁾



▼ Version with DA control valve1)



Correlation of direction of rotation, control and flow direction											
Direction of rotation	clockwise				counter-clo	counter-clockwise					
Size	28 to 56		71 to 125		28 to 56		71 to 125	71 to 125			
Control pressure	X ₁	X ₂									
Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A			
Working pressure	M _B	M _A	M _A	M _B	M _A	M _B	M _B	M _A			

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HD - Proportional control, hydraulic, pilot-pressure related

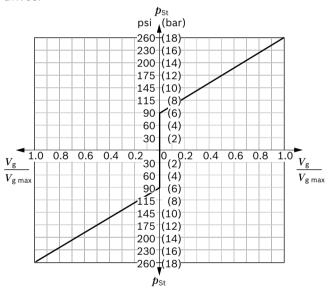
The output flow of the pump is infinitely variable between 0 and 100%, proportional to the difference in pilot pressure applied to the two pilot pressure ports $(Y_1 \text{ and } Y_2)$.

The pilot signal, coming from an external source, is a pressure signal. Flow is negligible, as the pilot signal acts only on the control spool of the control valve.

This control spool then directs control oil into and out of the stroking cylinder to adjust pump displacement as required.

A feedback lever connected to the stroking piston maintains the pump flow for any given pilot signal within the control range.

If the pump is also equipped with a DA control valve (see page 19), automotive operation is possible for travel drives.

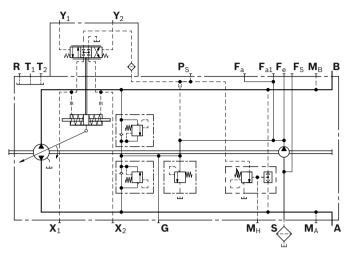


- V_g = Displacement at p_{St} $V_{g max}$ = Displacement at p_{St} = 260 psi (18 bar)
- Pilot signal p_{St} = 87 to 260 psi (6 to 18 bar) (at port Y₁, Y₂)
- ► Start of control at 87 psi (6 bar)
- ► End of control at 260 psi (18 bar) (maximum displacement $V_{\rm g \ max}$)

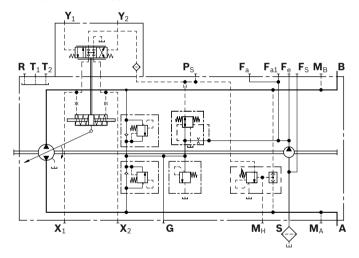
Notice

In the neutral position, the HD control module must be vented to reservoir via the external pilot control device.

▼ Standard version¹⁾

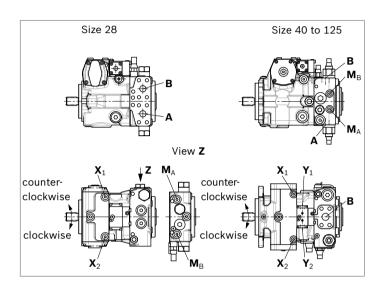


▼ Version with DA control valve¹⁾



¹⁾ Size 28 without port F_{a1} and F_{S}

Correlation of direction of rotation, control and flow direction											
Direction of rotation	clockwise				counter-cl	counter-clockwise					
Size	28 to 56	28 to 56			28 to 56		71 to 125				
Pilot signal	Y ₁	Y ₂									
Control pressure	X ₁	X ₂									
Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A			
Working pressure	M _R	MΔ	MΔ	MB	MA	M _R	M _□	MΔ			

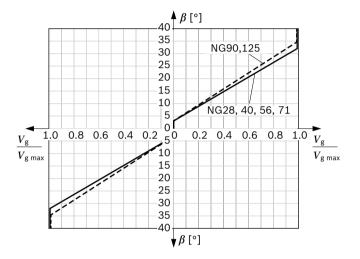


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HW - Proportional control, hydraulic, mechanical servo

The output flow of the pump is infinitely variable between 0 and 100%, proportional to the swivel angle of the control lever.

A feedback lever connected to the stroking piston maintains the pump flow for any given position of the control lever. If the pump is also equipped with a DA control valve (see page 19), automotive operation is possible for travel drives.



Swivel angle β at the control lever for pump displacement change:

- ► Start of control at β = ±3°
- End of control at β (max. displacement $V_{g \text{ max}}$)
 - Size 28 to 71 at ±32°
 - Size 90 to 125 at ±34.5°
- ▶ Rotational limit β of the control lever (internal) ±38° The maximum required torque at the lever is 15 lb-in (170 Ncm). To prevent damage to the HW control module, a positive mechanical stop of 36.5° ± 1 must be provided for the HW control lever on the customer side.

Notice

- Spring centering enables the pump, depending on pressure and speed, to move automatically to the neutral position (V_g = 0) as soon as there is no longer any torque on the control lever of the HW control module.
- ► If necessary, the position of the lever can be changed.

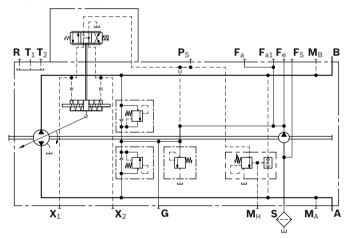
 The procedure is defined in the instruction manual.
- ▶ On delivery, the position of the lever may differ from that shown in the drawing.

Option: Neutral position switch

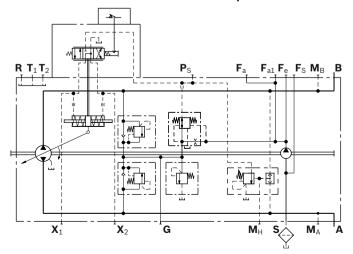
The switch contact in the neutral position switch is closed when the control lever on the HW control module is in its neutral position. The switch opens when the control lever is moved out of the central position in either direction. Thus, the neutral position switch provides a monitoring function for drive units that require the pump to be in the neutral position during certain operating conditions (e.g. starting diesel engines).

Technical Data	
Load capacity	20 A (continuous), without switching operations
Switching capacity	15 A / 32 V (resistive load)
	4 A / 32 V (inductive load)
Connector version	DEUTSCH DT04-2P-EP04
	(mating connector, see page 62)

▼ Standard version¹⁾

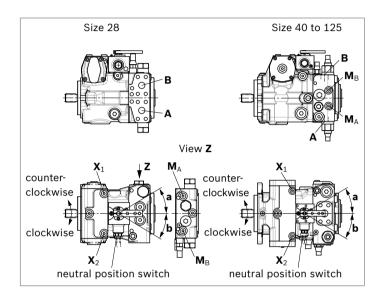


▼ Version with DA control valve and neutral position switch¹)



¹⁾ Size 28 without port \mathbf{F}_{a1} and \mathbf{F}_{S}

Correlation of direction of	of rotation, conti	ol and flow d	irection					
Direction of rotation	clockwise				counter-c	ockwise		
Size	28 to 56		71 to 125		28 to 56		71 to 125	
Lever direction	а	b	а	b	a	b	а	b
Control pressure	X ₂	X ₁						
Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B
Working pressure	M _A	M _B	M _B	MA	M _B	MA	M _A	M _B



EP - Proportional control, electric

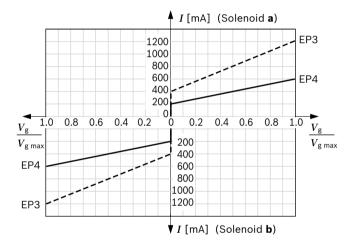
The output flow of the pump is infinitely variable between 0 and 100%, proportional to the electrical current supplied to solenoid **a** or **b**.

The electrical energy is converted into a force acting on the control spool.

This control spool then directs control oil into and out of the stroking cylinder to adjust pump displacement as required.

A feedback lever connected to the stroking piston maintains the pump flow for any given current within the control range.

If the pump is also equipped with a DA control valve (see page 19), automotive operation is possible for travel drives.



Notice

The proportional solenoids do not have manual override. Proportional solenoids with manual override and spring return are available on request.

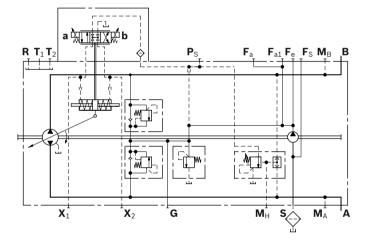
Technical data, solenoid	EP3	EP4
Voltage	12 V (±20%)	24 V (±20%)
Control current		
Start of control at $V_g = 0$	400 mA	200 mA
End of control at $V_{g\;max}$	1200 mA	600 mA
Current limit	1.54 A	0.77 A
Nominal resistance (at 68 °F (20 °C))	5.5 Ω	22.7 Ω
Dither		
Frequency	100 Hz	100 Hz
Minimum oscillation range ¹⁾	240 mA	120 mA
Duty cycle	100%	100%
Dither Frequency Minimum oscillation range ¹⁾	100 Hz 240 mA	120 mA

Type of protection: see connector version page 62

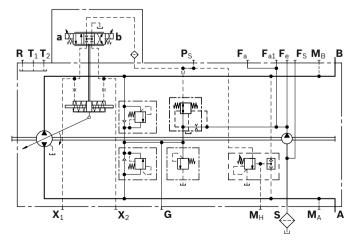
Various BODAS controllers with application software and amplifiers are available for controlling the proportional solenoids.

Further information can also be found on the Internet at www.boschrexroth.com/mobile-electronics

▼ Standard version²⁾



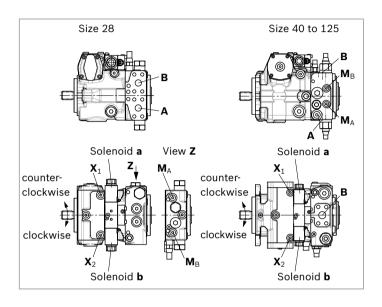
▼ Version with DA control valve²⁾



¹⁾ Minimum required oscillation range of the control current $\Delta I_{\rm p-p}$ (peak to peak) within the respective control range (start of control to end of control)

²⁾ Size 28 without port \boldsymbol{F}_{a1} and \boldsymbol{F}_{S}

Correlation of direction of	f rotation, contr	ol and flow d	irection					
Direction of rotation	clockwise				counter-c	lockwise		
Size	28 to 56		71 to 125		28 to 56		71 to 125	
Actuation of solenoid	а	b	а	b	а	b	а	b
Control pressure	X ₁	X ₂	X_1	X ₂	X ₁	X ₂	X_1	X ₂
Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A
Working pressure	M _B	M _A	M _A	M _B	M _A	M _B	M _B	M _A



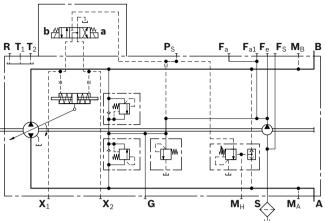
EZ - Two-point control, electric

By actuating either switching solenoid **a** or **b**, internal control pressure is applied directly to the stroking piston and the pump swivels to maximum displacement. The EZ control enables pump flow to be switched between $V_{\rm g}$ = 0 and $V_{\rm g \ max}$.

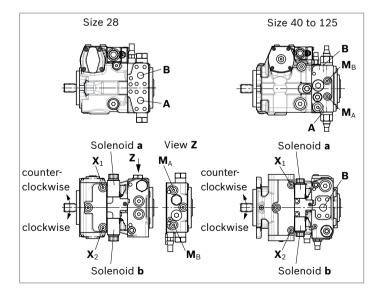
Flow direction is determined by which solenoid is energized.

Technical data, solenoid	EZ1	EZ2
Voltage	12 V (±20%)	24 V (±20%)
Neutral position $V_g = 0$	de-energized	de-energized
Position $V_{g\;max}$	energized	energized
Nominal resistance (at 68 °F (20 °C))	5.5 Ω	21.7 Ω
Nominal power	26.2 W	26.5 W
Minimum active current required	1.32 A	0.67 A
Duty cycle	100%	100%
Type of protection: see connector vers	ion page 62	

▼ Standard version¹⁾



Correlation of direction of rotation, control and flow direction										
Direction of rotation	clockwise				counter-c	ockwise				
Size	28 to 56		71 to 125		28 to 56		71 to 125			
Actuation of solenoid	а	b	а	b	а	b	а	b		
Control pressure	X ₂	X ₁								
Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B		
Working pressure	M _A	M _B	M _B	M _A	M _B	M _A	M _A	M _B		



¹⁾ Size 28 without port \boldsymbol{F}_{a1} and \boldsymbol{F}_{S}

DA - Automatic control, speed related

The DA closed loop control is an engine speed-dependent system for travel drives. The built-in DA control valve generates a pilot pressure that is proportional to pump (engine) drive speed. This pilot pressure is directed to the stroking cylinder of the pump by an electromagnetically actuated 4/3-way directional valve. The pump displacement is infinitely variable in each flow direction and is influenced by both pump drive speed and system pressure. The flow direction (e.g. machine moving forward or backward) is determined by either solenoid **a** or **b** being activated. Increasing the pump drive speed generates a higher pilot pressure from the DA control valve, with a subsequent increase in pump flow.

Depending on the selected pump operating characteristics, increasing system pressure (e.g. machine load) causes the pump to swivel back towards a smaller displacement. An overload protection for the engine (against stalling) is achieved by combining this pressure-dependent reduction in pump stroke with a reduction in pilot pressure as the engine speed drops.

Any additional power requirement, e.g. for hydraulic functions from attachments, could cause the engine speed to drop further. This will cause a further reduction in pilot pressure and thus of the pump displacement. Automatic power distribution and full exploitation of the available power are achieved in this way, both for the travel drive and for the implement hydraulics, with priority given to the implement hydraulics.

Various override options are available for DA control function to allow controlled operation of the implement hydraulics with high rpm at reduced vehicle speed.

The DA control valve can also be used in pumps with EP, DG, HW and HD control modules to protect the combustion engine against overload.

Notice

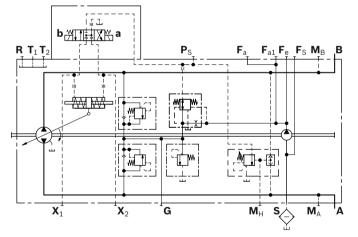
DA closed loop control is only suitable for certain types of travel drive systems and requires review of the engine and vehicle parameters to ensure that the pump is used correctly and that machine operation is safe and efficient. We recommend that all DA applications be reviewed by a Bosch Rexroth application engineer.

Technical data, solenoid	DA1	DA2
Voltage	12 V (±20%)	24 V (±20%)
Neutral position $V_g = 0$	de-energized	de-energized
Position $V_{g\;max}$	energized	energized
Nominal resistance (at 68 °F (20° C))	5.5 Ω	21.7 Ω
Nominal power	26.2 W	26.5 W
Minimum required active current	1.32 A	0.67 A
Duty cycle	100%	100%
Type of protection: see connector vers	sion page 62	

DA..2 - DA control valve, fixed setting

Pilot pressure is generated in relation to drive speed.

▼ DA control valve, fixed setting, DA1D2/DA2D2¹)



¹⁾ Size 28 without port \mathbf{F}_{a1} and \mathbf{F}_{S}

DA..3 - DA control valve, mechanically adjustable with position lever

Pilot pressure is generated in relation to drive speed. Any reduction of pilot pressure possible, independently of drive speed, through mechanical actuation of the position lever (inch function).

The maximum permissible actuation torque at the position lever is T_{max} = 3 lb-ft (4 Nm).

Maximum angle of rotation 70°, lever position: any.

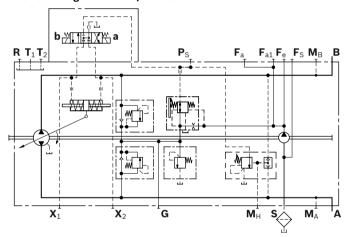
DA..3R

Direction of actuation of the position lever: clockwise

DA..3L

Direction of actuation of the position lever: counter-clockwise

▼ Circuit diagram DA1D3/DA2D3¹)



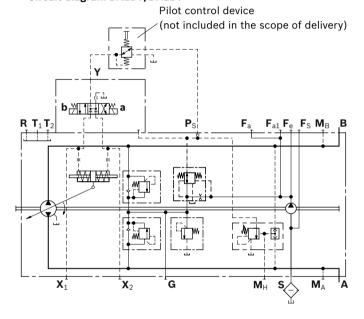
DA..7 - DA control valve, fixed setting, ports for pilot control device as inch valve

Any reduction of the pilot pressure possible, independent of the drive speed is achieved by the mechanical actuation of the pilot control device.

The pilot control device is installed separately from the pump (for example in the driver's cabin) and connected to the pump by two hydraulic control lines via ports \mathbf{P}_{S} and \mathbf{Y} . A suitable pilot control device must be ordered separately and is not included in the scope of delivery.

Note: Rotary inch valves, see page 63.

▼ Circuit diagram DA1D7/DA2D7¹)



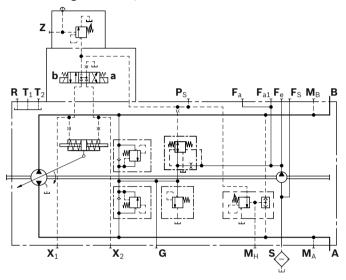
DA..8 - DA control valve, fixed setting and brake inch valve mounted

Only for pumps with DA control module

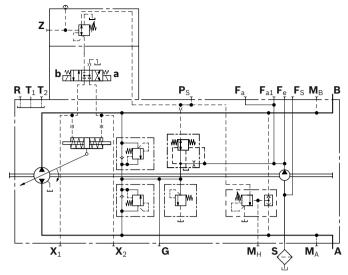
- ▶ Version with throttle valve size 28, 40, 56, 71
- ► Version with pressure reducing valve size 90, 125
 Permits reduction of the pilot pressure, independently of the drive speed via hydraulic control (port **Z**).

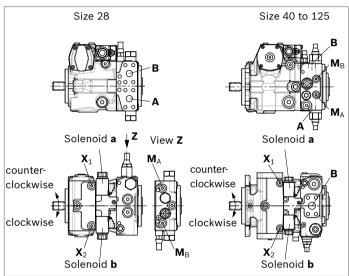
Control at port **Z** by means of brake fluid based on mineral oil.

▼ Circuit diagram DA1D8/DA2D8 with throttle valve1)



▼ Circuit diagram DA1D8/DA2D8 with pressure reducing valve¹)





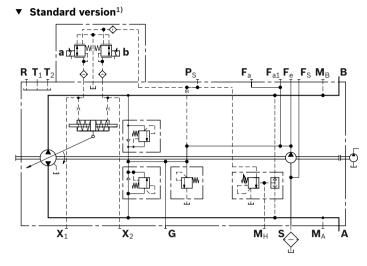
Correlation of direction of	rotation, contr	ol and flow d	irection						
Direction of rotation	clockwise			'	counter-c	counter-clockwise			
Size	28 to 56		71 to 125		28 to 56		71 to 125		
Actuation of solenoid	а	b	a	b	a	b	a	b	
Control pressure	X ₂	X ₁							
Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B	
Working pressure	M _A	M _B	M _B	M _A	M _B	M _A	M _A	M _B	

¹⁾ Size 28 without port \boldsymbol{F}_{a1} and \boldsymbol{F}_{S}

ET - Electric control, direct operated

The output flow of the pump is infinitely variable between 0 to 100%. Depending on the preselected current \mathbf{I} at solenoids \mathbf{a} and \mathbf{b} of the pressure reducing valves, the stroking cylinder of the pump is proportionally supplied with control pressure. The two control pressures \mathbf{X}_1 and \mathbf{X}_2 can be controlled independently. The pump displacement that arises at a certain control current is dependent on the speed and working pressure of the pump. A different flow direction is associated with each pressure reducing valve. Maximum permissible control pressure \mathbf{P}_S : 580 psi (40 bar).

Technical data, solenoid	ET5	ET6
Voltage	12 V (±20%)	24 V (±20%)
Current limit	1.54 A	0.77 A
Nominal resistance (at 68 °F (20 °C))	5.5 Ω	22.7 Ω
Dither		
Frequency	100 Hz	100 Hz
Minimum oscillation range ¹⁾	240 mA	120 mA
Duty cycle	100%	100%
Type of protection: see connector vers	ion page 62	



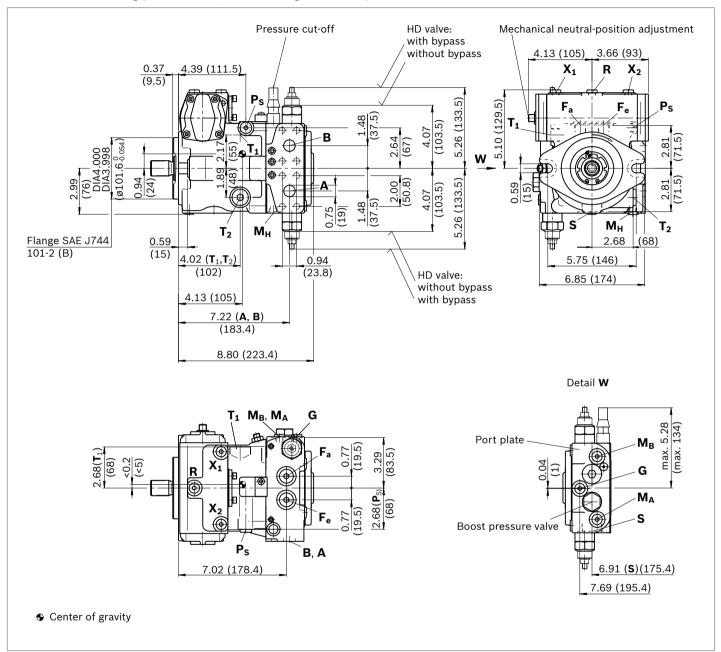
Correlation of direction of	f rotation, contr	ol and flow d	irection					
Direction of rotation	clockwise		,		counter-c	lockwise		
Size	28 to 56		71		28 to 56		71	
Actuation of solenoid	а	b	а	b	а	b	а	b
Control pressure	X ₁	X ₂						
Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A
Working pressure	M _B	M _A	M _A	M _B	M _A	M _B	M _B	M _A

¹⁾ Size 28 without port \boldsymbol{F}_{a1} and \boldsymbol{F}_{S}

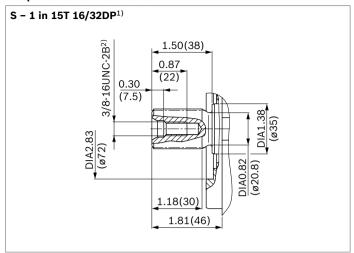
Dimensions, size 28

NV - Version without control module

Standard: SAE working port **A** and **B**, same side right, suction port **S** bottom (60)



▼ Splined shaft ANSI B92.1a



Ports		Standard	Size	p _{max} [psi (bar)] ³⁾	State ⁸⁾
A, B	Working port	SAEJ518 ⁴⁾	3/4 in	6500 (450)	0
	Fastening thread	ISO 68	3/8 in -16 UNC-2B; 0.67 (17) deep		
S	Suction port	ISO 11926 ⁷⁾	1 5/16 in -12 UN-2B; 0.79 (20) deep	75 (5)	O ⁵⁾
T ₁	Drain port	ISO 11926 ⁷⁾	7/8 in -14 UNF-2B; 0.67 (17) deep	45 (3)	O ⁶⁾
T ₂	Drain port	ISO 11926 ⁷⁾	7/8 in -14 UNF-2B; 0.67 (17) deep	45 (3)	X ₆)
R	Air bleed port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	45 (3)	Х
$\mathbf{X}_1, \mathbf{X}_2$	Control pressure port (upstream of orifice)	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Χ
G	Boost pressure port inlet	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Χ
Ps	Pilot pressure port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
M _A , M _B	Measuring port pressure A, B	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
M _H	Measuring port, high pressure	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
F _a	Boost pressure port inlet	ISO 11926 ⁷⁾	3/4 in -16 UNF-2B; 0.59 (15) deep	580 (40)	Х
F _e	Boost pressure port outlet	ISO 11926 ⁷⁾	3/4 in -16 UNF-2B; 0.59 (15) deep	580 (40)	Х
Z	Pilot pressure port (inch signal DA8 only)	DIN 3852 ⁷⁾	M10 x 1; 0.31 (8) deep	580 (40)	Х

Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

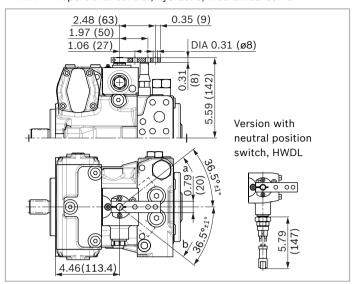
 $_{5)}$ Plugged for external boost pressure supply.

⁶⁾ Depending on installation position, T₁ or T₂ must be connected (see also installation instructions on page 65).

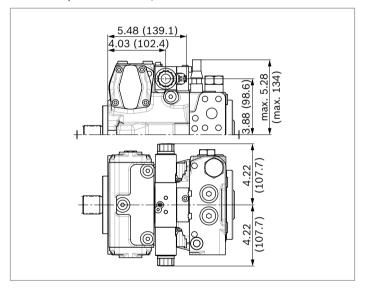
⁷⁾ The countersink can be deeper than as specified in the standard.

⁸⁾ O = Must be connected (plugged when delivered)X = Plugged (observe installation instructions)

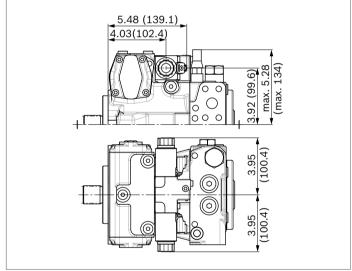
▼ HW - Proportional control, hydraulic, mechanical servo



▼ **EP** – Proportional control, electric

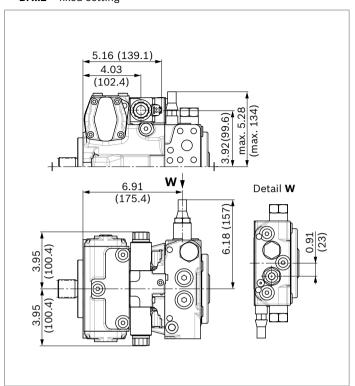


▼ **EZ** – Two-point control, electric

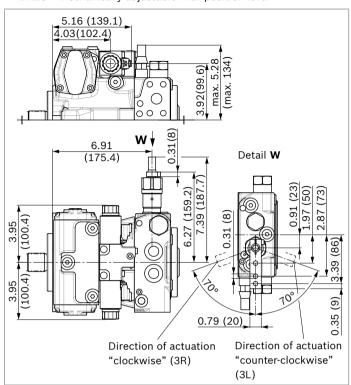


DA control valve

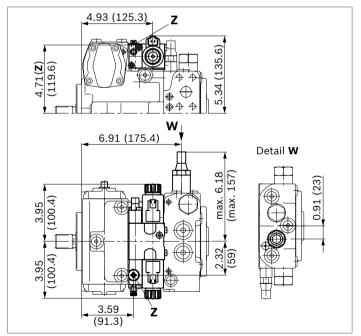
▼ DA..2 – fixed setting



▼ DA..3 - Mechanically adjustable with position lever



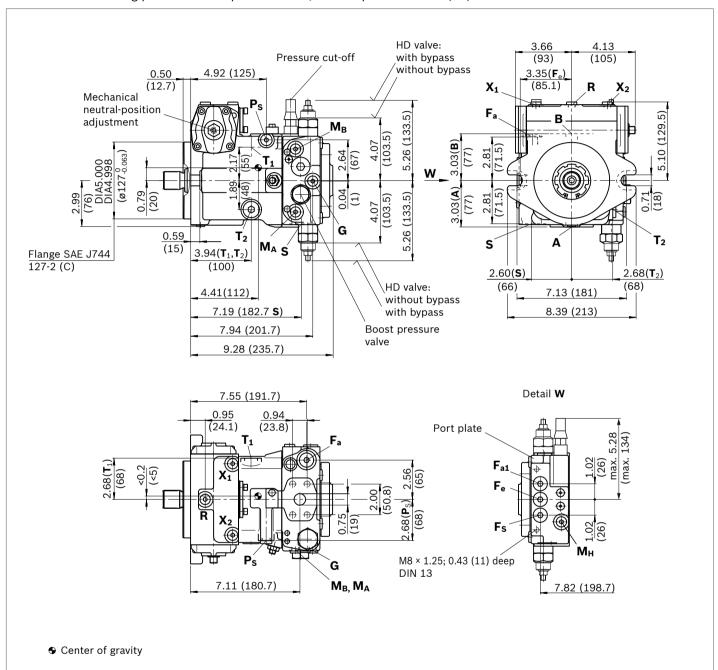
▼ DA..8 - Fixed setting and inch valve mounted



Dimensions, size 40

NV - Version without control module

Standard: SAE working port A and B top and bottom, suction port S bottom (52)



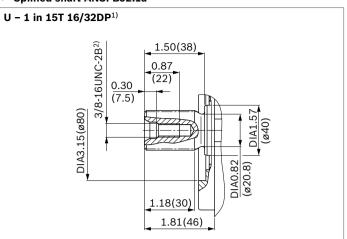
Notice

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (53), port plate 52 rotated through 180°, installation drawing on request

▼ Splined shaft ANSI B92.1a

S - 1 1/4 in 14T 12/24DP¹) 1.89(48) 1.10 (28) (9.5) 1.57(40) 2.20(56)

▼ Splined shaft ANSI B92.1a



Ports		Standard	Size	p _{max} [psi (bar)] ³⁾	State ⁸⁾
A, B	Working port	SAEJ518 ⁴⁾	3/4 in	6500 (450)	0
	Fastening thread	ASME B1.1	3/8 in -16 UNC-2B; 0.67 (17) deep		
S	Suction port	ISO 11926 ⁷⁾	1 5/16 in -12 UN-2B; 0.79 (20) deep	75 (5)	O ⁵⁾
T ₁	Drain port	ISO 11926 ⁷⁾	7/8 in -14 UNF-2B; 0.67 (17) deep	45 (3)	O ⁶⁾
T ₂	Drain port	ISO 11926 ⁷⁾	7/8 in -14 UNF-2B; 0.67 (17) deep	45 (3)	X ⁶⁾
R	Air bleed port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	45 (3)	Х
X ₁ , X ₂	Control pressure port (upstream of orifice)	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	X
G	Boost pressure port inlet	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Х
P _S	Pilot pressure port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
M _A , M _B	Measuring port pressure A, B	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
M _H	Measuring port, high pressure	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
F _a	Boost pressure port inlet	ISO 11926 ⁷⁾	3/4 in -16 UNF-2B; 0.51 (13) deep	580 (40)	Х
F _{a1}	Boost pressure port inlet (attachment filter)	DIN 3852 ⁷⁾	M18 x 1.5; 0.47 (12) deep	580 (40)	Х
Fe	Boost pressure port outlet	DIN 3852 ⁷⁾	M18 x 1.5; 0.47 (12) deep	580 (40)	Х
Fs	Line from filter to suction port (cold start)	DIN 3852 ⁷⁾	M18 x 1.5; 0.47 (12) deep	580 (40)	Х
Z	Pilot pressure port (inch signal DA8 only)	DIN 3852 ⁷⁾	M10 x 1; 0.31 (8) deep	580 (40)	X

Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

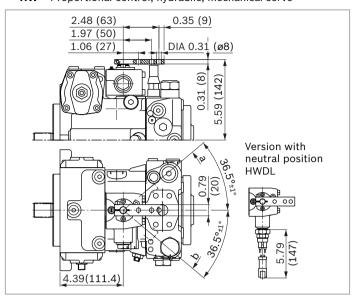
⁵⁾ Plugged for external boost pressure supply.

⁶⁾ Depending on installation position, T_1 or T_2 must be connected (see also installation instructions on page 65).

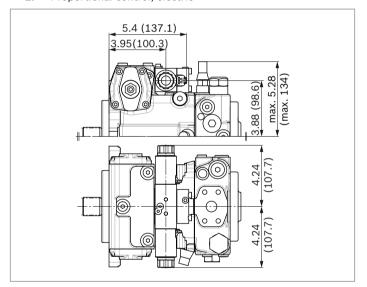
⁷⁾ The countersink can be deeper than as specified in the standard.

 ⁸⁾ O = Must be connected (plugged when delivered)
 X = Plugged (in normal operation)

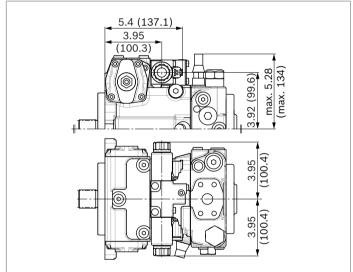
▼ HW - Proportional control, hydraulic, mechanical servo



▼ EP - Proportional control, electric

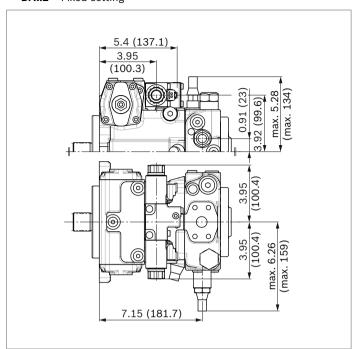


▼ EZ - Two-point control, electric

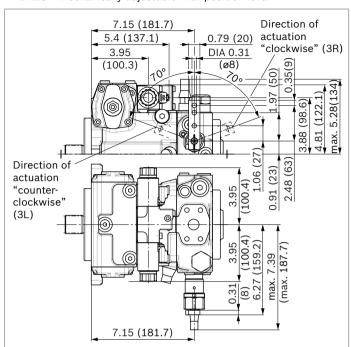


DA control valve

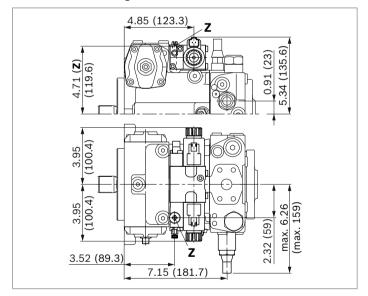
▼ DA..2 - Fixed setting



▼ DA..3 - Mechanically adjustable with position lever



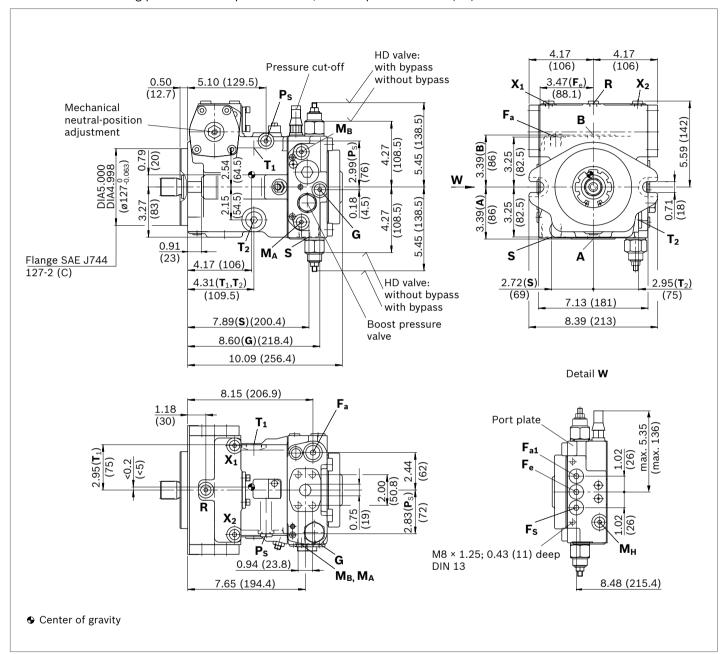
▼ DA..8 - Fixed setting and inch valve mounted



Dimensions, size 56

NV - Version without control module

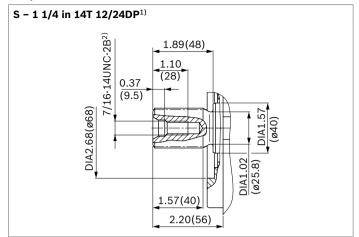
Standard: SAE working port A and B top and bottom, suction port S bottom (52)



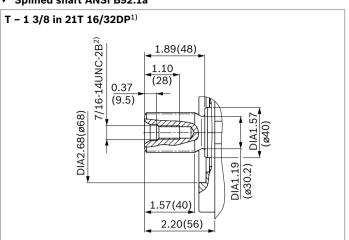
Notice

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (53), port plate 52 rotated through 180°, installation drawing on request

▼ Splined shaft ANSI B92.1a



▼ Splined shaft ANSI B92.1a



Ports		Standard	Size	p _{max} [psi (bar)] ³⁾	State ⁹⁾
A, B	Working port	SAEJ518 ⁴⁾	3/4 in	6500 (450)	0
	Fastening thread	ASME B1.1	3/8 in -16 UNC-2B; 0.67 (17) deep		
S	Suction port	ISO 11926 ⁷⁾	1 5/16 in -12 UN-2B; 0.79 (20) deep	75 (5)	O ⁵⁾
T ₁	Drain port	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	O ⁶⁾
T ₂	Drain port	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	X ₆)
R	Air bleed port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	45 (3)	Х
X ₁ , X ₂	Control pressure port (upstream of orifice)	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Х
X ₁ , X ₂	Control pressure port (upstream of orifice, DG only)	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	0
X ₃ , X ₄ ⁸⁾	Stroking chamber pressure port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Х
G	Boost pressure port inlet	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
Ps	Pilot pressure port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
M _A , M _B	Measuring port pressure A, B	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
M _H	Measuring port, high pressure	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
F a	Boost pressure port inlet	ISO 11926 ⁷⁾	3/4 in -16 UNF-2B; 0.59 (15) deep	580 (40)	Х
F _{a1}	Boost pressure port inlet (attachment filter)	DIN 3852 ⁷⁾	M18 x 1.5; 0.47 (12) deep	580 (40)	Х
F _e	Boost pressure port outlet	DIN 3852 ⁷⁾	M18 x 1.5; 0.47 (12) deep	580 (40)	Х
Fs	Line from filter to suction port (cold start)	DIN 3852 ⁷⁾	M18 x 1.5; 0.47 (12) deep	580 (40)	Χ
Y ₁ , Y ₂	Pilot pressure port (pilot signal HD only)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	0
Z	Pilot pressure port (inch signal DA8 only)	DIN 3852 ⁷⁾	M10 x 1; 0.31 (8) deep	580 (40)	Χ

¹⁾ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

⁵⁾ Plugged for external boost pressure supply.

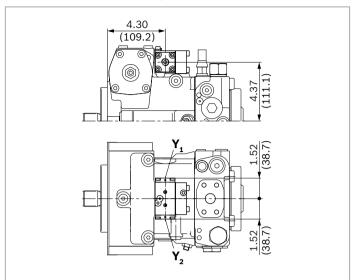
⁶⁾ Depending on installation position, T₁ or T₂ must be connected (see also installation instructions on page 65).

⁷⁾ The countersink can be deeper than as specified in the standard.

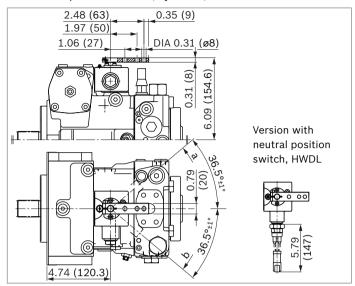
⁸⁾ Optional, see page 55

⁹⁾ O = Must be connected (plugged when delivered)X = Plugged (in normal operation)

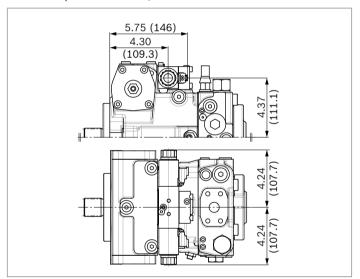
▼ HD - Proportional control, hydraulic, pilot-pressure related



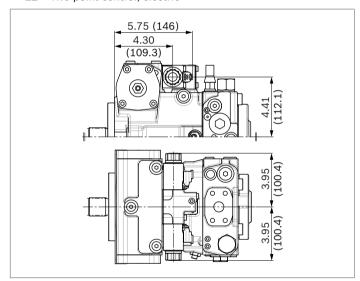
▼ HW - Proportional control, hydraulic, mechanical servo



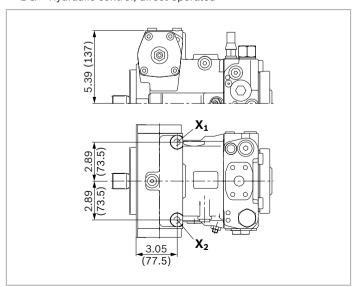
▼ **EP** – Proportional control, electric



▼ **EZ** – Two-point control, electric



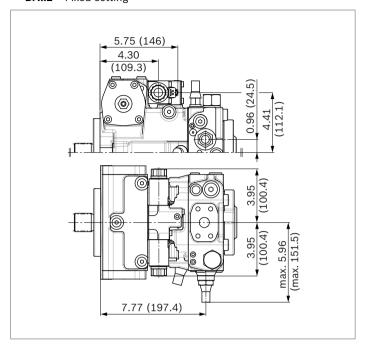
▼ **DG** – Hydraulic control, direct operated



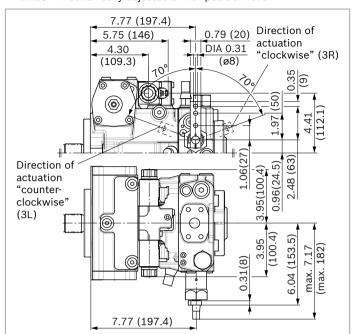
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DA control valve

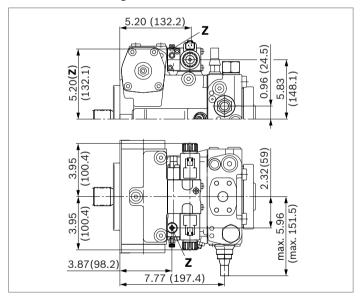
▼ DA..2 - Fixed setting



▼ DA..3 - Mechanically adjustable with position lever



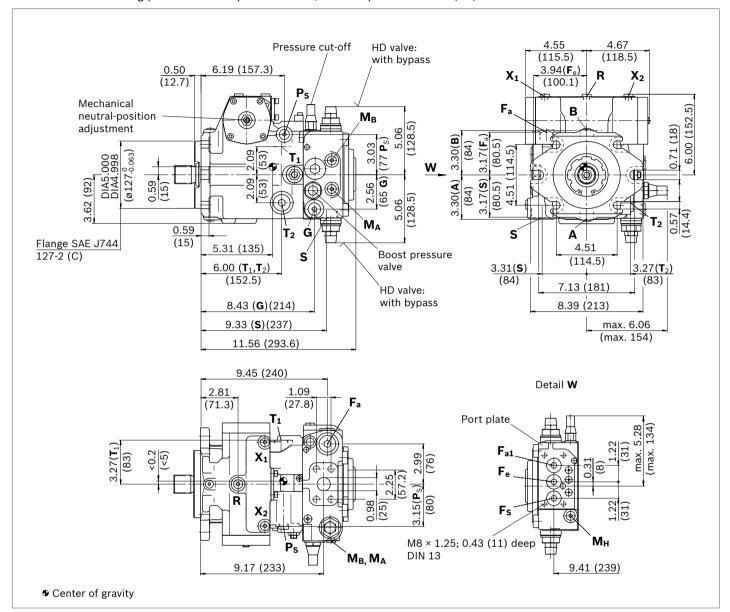
▼ DA..8 - Fixed setting and inch valve mounted



Dimensions, size 71

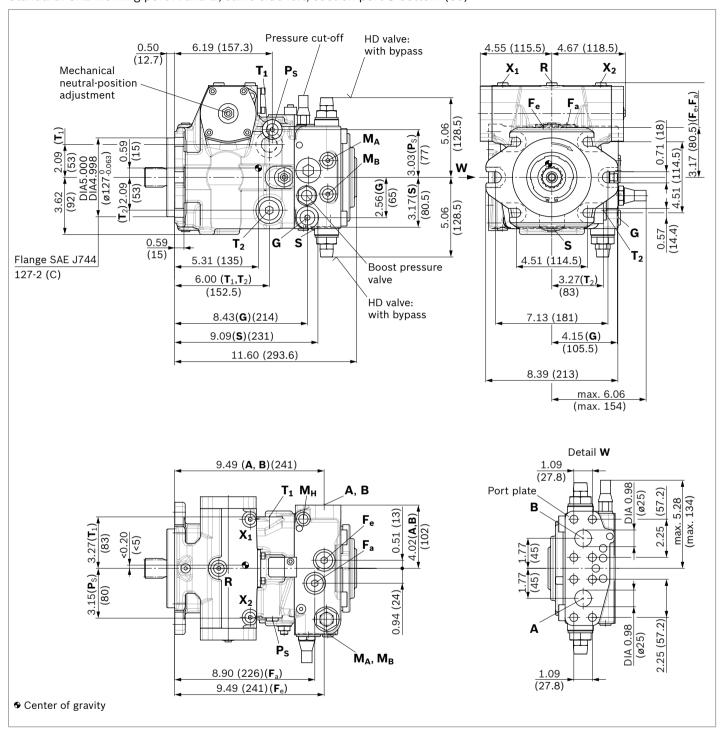
NV - Version without control module

Standard: SAE working port A and B top and bottom, suction port S bottom (52)



NV - Version without control module

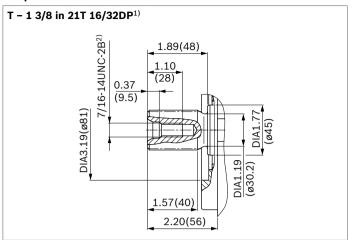
Standard: SAE working port **A** and **B**, same side left, suction port **S** bottom (60)



▼ Splined shaft ANSI B92.1a

S - 1 1/4 in 14T 12/24DP¹) 1.89(48) 1.10 (28) (9.5) 1.57(40) 2.20(56)

▼ Splined shaft ANSI B92.1a



Ports		Standard	Size	p _{max} [psi (bar)] ³⁾	State ⁹⁾
A, B	Working port	SAEJ518 ⁴⁾	1 in	6500 (450)	0
	Fastening thread	ASME B1.1	7/16 in -14 UNC-2B; 0.67 (17) deep		
S	Suction port	ISO 11926 ⁷⁾	1 5/8 in -12 UN-2B; 0.79 (20) deep	75 (5)	O ⁵⁾
T ₁	Drain port	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	O ⁶⁾
T ₂	Drain port	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	X ₆)
R	Air bleed port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	45 (3)	X
X ₁ , X ₂	Control pressure port (upstream of orifice)	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Х
X ₁ , X ₂	Control pressure port (upstream of orifice, DG only)	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	0
X ₃ , X ₄ ⁸⁾	Stroking chamber pressure port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Х
G	Boost pressure port inlet	ISO 11926 ⁷⁾	3/4 in -16 UNF-2B; 0.59 (15) deep	580 (40)	Х
Ps	Pilot pressure port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
M _A , M _B	Measuring port pressure A, B	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
M _H	Measuring port, high pressure	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
F a	Boost pressure port inlet	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	580 (40)	X
F _{a1}	Boost pressure port inlet (attachment filter)	DIN 3852 ⁷⁾	M22 x 1.5; 0.55 (14) deep	580 (40)	Х
F _e	Boost pressure port outlet	DIN 3852 ⁷⁾	M22 x 1.5; 0.55 (14) deep	580 (40)	Х
Fs	Line from filter to suction port (cold start)	DIN 3852 ⁷⁾	M22 x 1.5; 0.55 (14) deep	580 (40)	Χ
Y ₁ , Y ₂	Pilot pressure port (pilot signal HD only)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	0
Z	Pilot pressure port (inch signal DA8 only)	DIN 3852 ⁷⁾	M10 x 1; 0.31 (8) deep	580 (40)	Χ

¹⁾ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

⁵⁾ Plugged for external boost pressure supply.

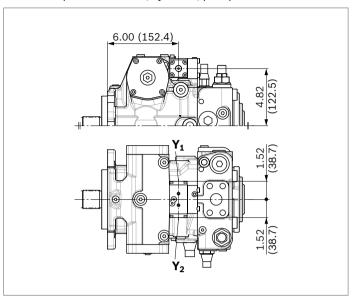
⁶⁾ Depending on installation position, T_1 or T_2 must be connected (see also installation instructions on page 65).

⁷⁾ The countersink can be deeper than as specified in the standard.

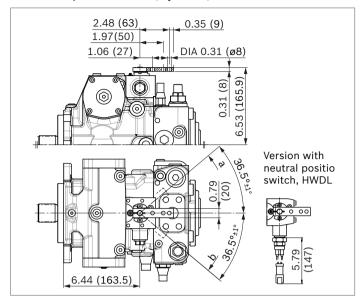
⁸⁾ Optional, see page 55

⁹⁾ O = Must be connected (plugged when delivered)X = Plugged (in normal operation)

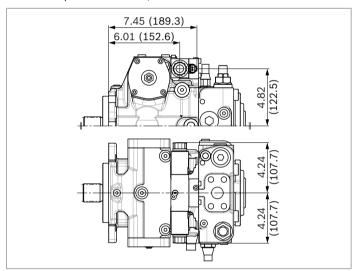
▼ HD - Proportional control, hydraulic, pilot-pressure related



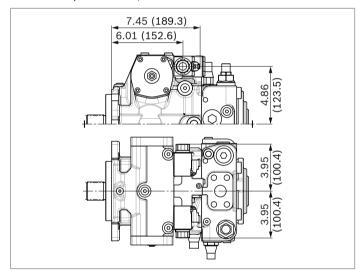
▼ HW - Proportional control, hydraulic, mechanical servo



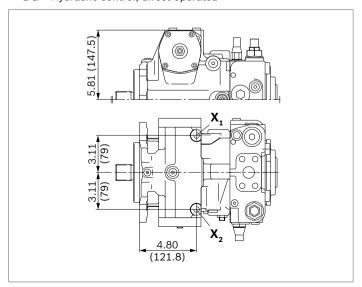
▼ EP - Proportional control, electric



▼ **EZ** – Two-point control, electric

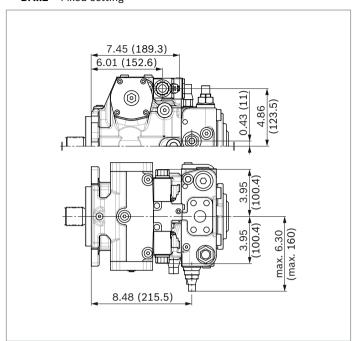


▼ **DG** – Hydraulic control, direct operated

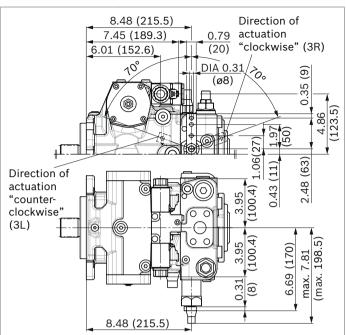


DA control valve

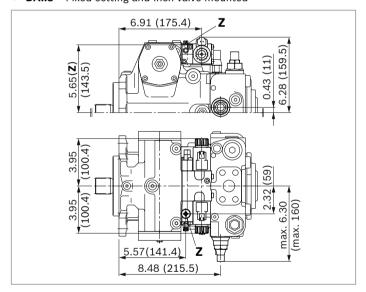
▼ DA..2 - Fixed setting



▼ DA..3 - Mechanically adjustable with position lever



▼ DA..8 - Fixed setting and inch valve mounted

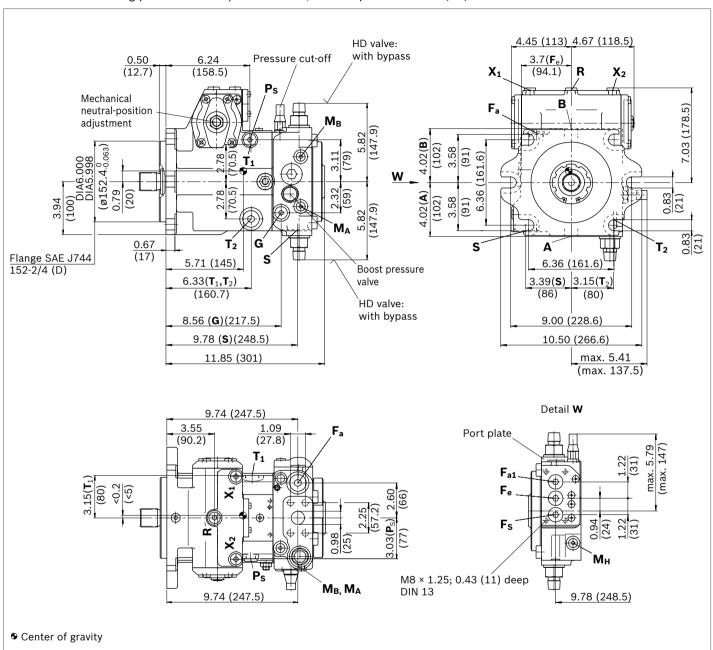


40

Dimensions, size 90

NV - Version without control module

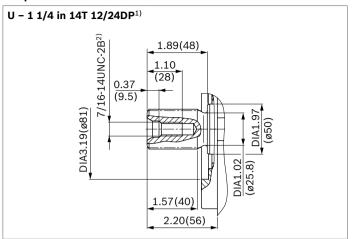
Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (52)



▼ Splined shaft ANSI B92.1a

S - 1 3/4 in 13T 8/16DP¹) 2.64(67) 1.42 (36) 2.17(55) 2.95(75)

▼ Splined shaft ANSI B92.1a



Ports		Standard	Size	p _{max} [psi (bar)] ³⁾	State ⁹⁾
A, B	Working port	SAEJ518 ⁴⁾	1 in	6500 (450)	0
	Fastening thread	ASME B1.1	7/16 in -14 UNC-2B; 0.67 (17) deep		
S	Suction port	ISO 11926 ⁷⁾	1 5/8 in -12 UN-2B; 0.79 (20) deep	75 (5)	O ⁵⁾
T ₁	Drain port	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	O ₆)
T_2	Drain port	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	X ⁶⁾
R	Air bleed port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	45 (3)	Χ
\mathbf{X}_1 , \mathbf{X}_2	Control pressure port (upstream of orifice)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	X
$\mathbf{X}_1, \mathbf{X}_2$	Control pressure port (upstream of orifice, DG only)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	0
X ₃ , X ₄ ⁸⁾	Stroking chamber pressure port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	X
G	Boost pressure port inlet	ISO 11926 ⁷⁾	3/4 in -16 UNF-2B; 0.59 (15) deep	580 (40)	X
Ps	Pilot pressure port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	X
M _A , M _B	Measuring port pressure A, B	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	X
M _H	Measuring port, high pressure	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	X
F _a	Boost pressure port inlet	ISO 11926 ⁷⁾	1 1/16 in -12 UN-2B; 0.79 (20) deep	580 (40)	X
F _{a1}	Boost pressure port inlet (attachment filter)	DIN 3852 ⁷⁾	M22 x 1.5; 0.55 (14) deep	580 (40)	X
Fe	Boost pressure port outlet	DIN 3852 ⁷⁾	M22 x 1.5; 0.55 (14) deep	580 (40)	X
Fs	Line from filter to suction port (cold start)	DIN 3852 ⁷⁾	M22 x 1.5; 0.55 (14) deep	580 (40)	X
Y ₁ , Y ₂	Pilot pressure port (pilot signal HD only)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	0
Z	Pilot pressure port (inch signal DA8 only)	DIN 3852 ⁷⁾	M10 x 1; 0.31 (8) deep	580 (40)	Х

¹⁾ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

⁵⁾ Plugged for external boost pressure supply.

⁶⁾ Depending on installation position, T₁ or T₂ must be connected (see also installation instructions on page 65).

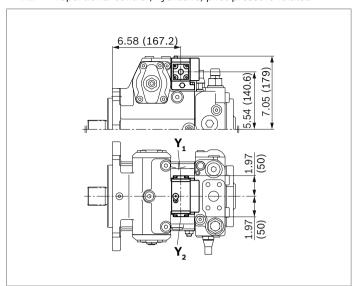
⁷⁾ The countersink can be deeper than as specified in the standard.

⁸⁾ Optional, see page 55

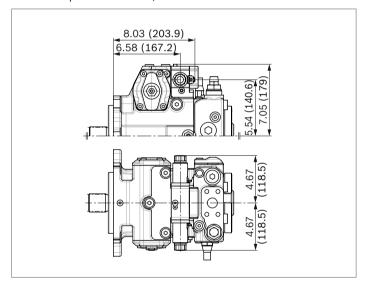
⁹⁾ O = Must be connected (plugged when delivered)X = Plugged (in normal operation)

42 **AA4VG Series 32** | Axial piston variable pump Dimensions, size 90

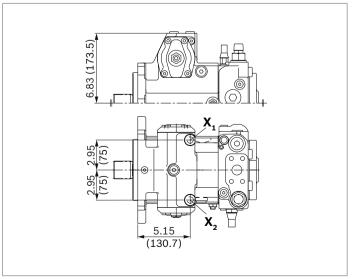
▼ HD - Proportional control, hydraulic, pilot-pressure related



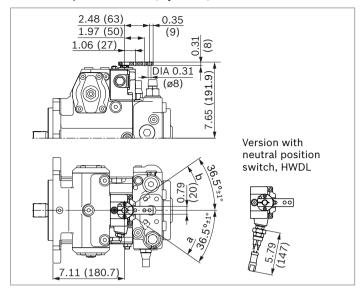
▼ **EP** – Proportional control, electric



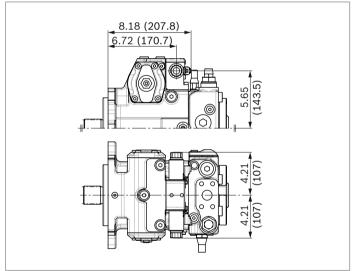
▼ **DG** - Hydraulic control, direct operated



▼ HW - Proportional control, hydraulic, mechanical servo

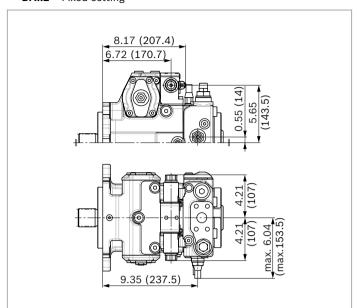


▼ EZ - Two-point control, electric

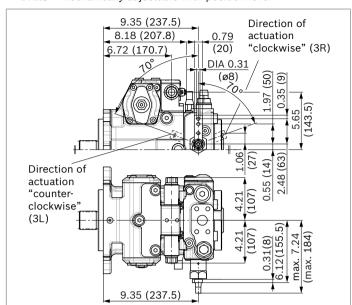


DA control valve

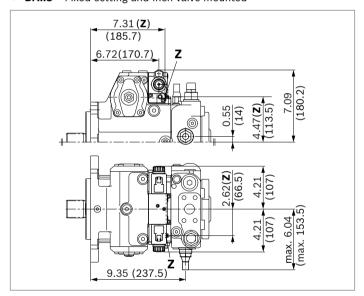
▼ DA..2 - Fixed setting



▼ DA..3 - Mechanically adjustable with position lever



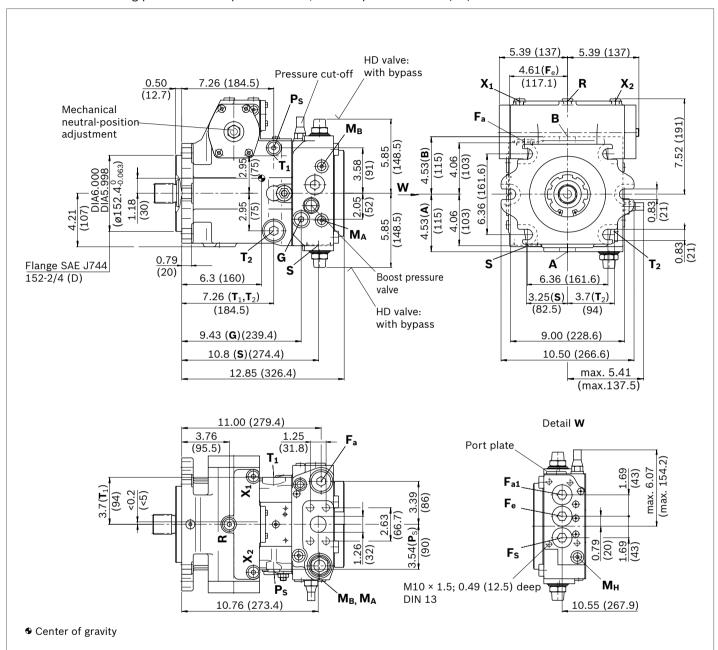
▼ DA..8 - Fixed setting and inch valve mounted



Dimensions, size 125

NV - Version without control module

Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (52)



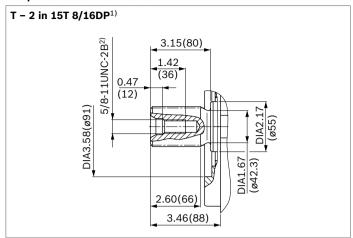
Notice

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (53). Port plate 52 rotated through 180°, installation drawing on request

▼ Splined shaft ANSI B92.1a

S - 1 3/4 in 13T 8/16DP¹ 2.64(67) 1.42 (12) 2.17(55) 2.95(75)

▼ Splined shaft ANSI B92.1a



Ports		Standard	Size	p _{max} [psi (bar)] ³⁾	State ⁹⁾
A, B	Working port	SAEJ518 ⁴⁾	1 1/4 in	6500 (450)	0
	Fastening thread	ASME B1.1	1/2 in -13 UNC-2B; 0.75 (19) deep		
S	Suction port	ISO 11926 ⁷⁾	1 7/8 in -12 UN-2B; 0.79 (20) deep	75 (5)	O ⁵⁾
T ₁	Drain port	ISO 11926 ⁷⁾	1 5/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	O ⁶⁾
T ₂	Drain port	ISO 11926 ⁷⁾	1 5/16 in -12 UN-2B; 0.79 (20) deep	45 (3)	X ⁶⁾
R	Air bleed port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	45 (3)	Х
X ₁ , X ₂	Control pressure port (upstream of orifice)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
X ₁ , X ₂	Control pressure port (upstream of orifice, DG only)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	0
X ₃ , X ₄ ⁸⁾	Stroking chamber pressure port	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	580 (40)	Х
G	Boost pressure port inlet	ISO 11926 ⁷⁾	7/8 in -14 UNF-2B; 0.67 (17) deep	580 (40)	Х
Ps	Pilot pressure port	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	Х
M _A , M _B	Measuring port pressure A, B	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
M _H	Measuring port, high pressure	ISO 11926 ⁷⁾	7/16 in -20 UNF-2B; 0.47 (12) deep	6500 (450)	Х
F a	Boost pressure port inlet	ISO 11926 ⁷⁾	1 5/16 in -12 UN-2B; 0.79 (20) deep	580 (40)	Х
F _{a1}	Boost pressure port inlet (attachment filter)	DIN 3852 ⁷⁾	M33 x 1.5; 0.71 (18) deep	580 (40)	Х
Fe	Boost pressure port outlet	DIN 3852 ⁷⁾	M33 x 1.5; 0.71 (18) deep	580 (40)	Х
Fs	Line from filter to suction port (cold start)	DIN 3852 ⁷⁾	M33 x 1.5; 0.71 (18) deep	580 (40)	Х
Y ₁ , Y ₂	Pilot pressure port (pilot signal HD only)	ISO 11926 ⁷⁾	9/16 in -18 UNF-2B; 0.51 (13) deep	580 (40)	0
Z	Pilot pressure port (inch signal DA8 only)	DIN 3852 ⁷⁾	M10 x 1; 0.31 (8) deep	580 (40)	Х

¹⁾ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

⁵⁾ Plugged for external boost pressure supply.

⁶⁾ Depending on installation position, T₁ or T₂ must be connected (see also installation instructions on page 65).

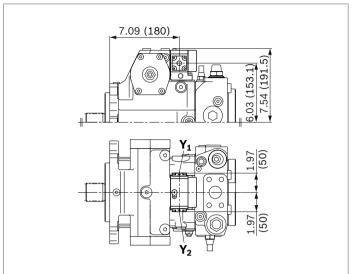
⁷⁾ The countersink can be deeper than as specified in the standard.

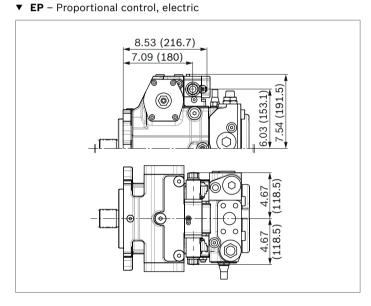
⁸⁾ Optional, see page 55

⁹⁾ O = Must be connected (plugged when delivered)X = Plugged (in normal operation)

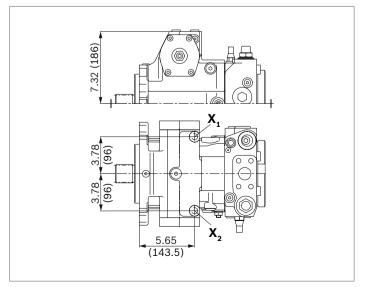
46 **AA4VG Series 32** | Axial piston variable pump Dimensions, size 125

▼ HD - Proportional control, hydraulic, pilot-pressure related

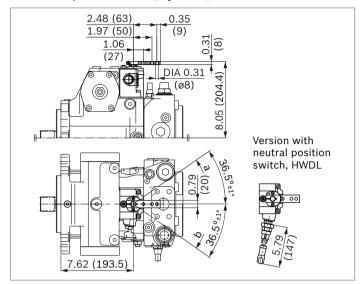




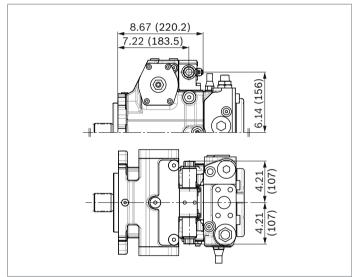
▼ DG - Hydraulic control, direct operated



▼ HW - Proportional control, hydraulic, mechanical servo

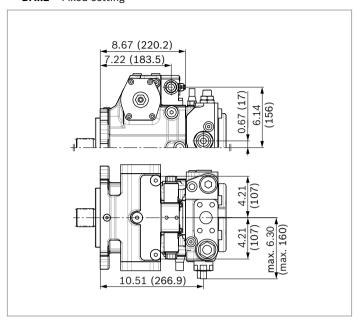


▼ EZ - Two-point control, electric

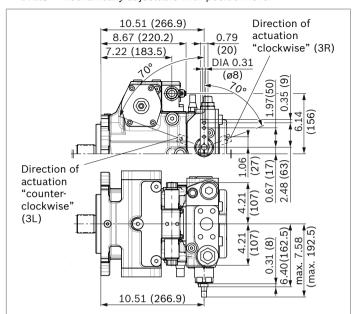


DA control valve

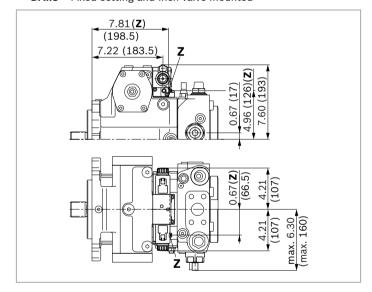
▼ DA..2 - Fixed setting



▼ DA..3 - Mechanically adjustable with position lever



▼ DA..8 - Fixed setting and inch valve mounted

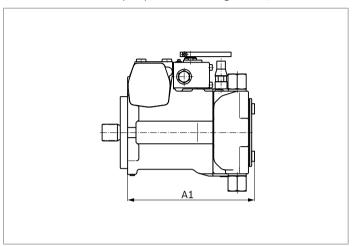


48

Dimensions, through drive

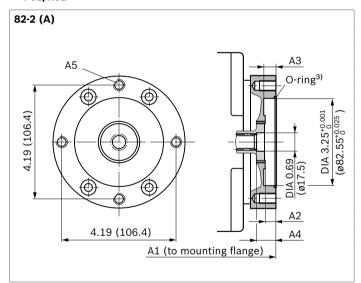
Flange SAE J744	Hub for splined shaft ¹⁾	28	40	56	71	90	125	Code
Without through drive		•	•	•	•	•	•	00
82-2 (A)	5/8 in 9T 16/32DP	•	•	•	•	•	•	01

▼ N00 - without boost pump, without through drive / F00 - with boost pump, without through drive



NG	A1 (N00)	A1 (F00)
28	8.42	8.80
	(213.9)	(223.4)
40	8.67	9.28
	(220.2)	(235.7)
56	9.43	10.09
	(239.4)	(256.4)
71	10.99	11.56
	(279.1)	(293.6)
90	11.30	11.85
	(287)	(301)
125	12.63	12.85
	(320.9)	(326.4)

▼ F01/K01⁴⁾



NG	A1 (F01)	A1 (K01)	A2		A4		
28	8.97	8.97	0.30	0.30	0.57		
	(227.9)	(227.9)	(7.5)	(7.5)	(14.5)		
40	9.44	9.22	0.35	0.35	0.71		
	(239.7)	(234.2)	(9)	(9)	(18)		
56	10.29	10.04	0.39	0.39	0.71		
	(261.4)	(254.9)	(10)	(10)	(18)		
71	11.72	11.72	0.35	0.39	0.67		
	(297.6)	(297.6)	(9)	(10)	(17)		
90	11.97	11.97	0.35	0.32	_		
	(304)	(304)	(9)	(8)	_		
125	13.03	13.03	0.41	0.35	_		
	(330.9)	(330.9)	(10.5)	(9)	-		
NG		A5 ²⁾					
28 to	125	3/8 in -16 UNC; 0.59 (15) deep					

Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

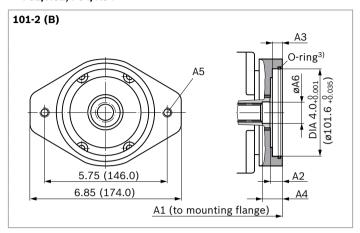
²⁾ Thread according to ASME B1.1

³⁾ O-ring included in the scope of delivery

⁴⁾ The illustration shows the 2-hole version. Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

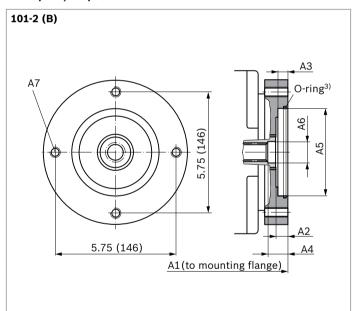
Flange SAE J744	Hub for splined shaft ¹⁾	28	40	56	71	90	125	Code
101-2 (B)	7/8 in 13T 16/32DP	•	•	•	•	•	•	02
	1 in 15T 16/32DP	•	•	•	•	•	•	04

▼ F02/K02; F04/K044)



	NG	A1	A2	A3	A4 (02)	A4 (04)	A5 ²⁾
	28	9.07	0.38	0.38	0.64	0.54	1/2 in -13 UNC;
		(230.4)	(9.7)	(9.7)	(16.2)	(13.7)	0.75 (19) deep
	40	9.48	0.43	0.435)	0.67	0.63	1/2 in -13 UNC;
		(240.7)	(11)	$(11)^{5)}$	(17)	(16)	0.75 (19) deep
	56 10.33		0.47	0.43	0.77	0.73	1/2 in -13 UNC;
		(262.4)	(12) (11)		(19.5)	(18.5)	0.75 (19) deep
			A6				
	F02/K02		DIA 0.94				
			(ø24)				
F04/K04		DIA 1.06					
		(ø27)		-,			

▼ F02/K02; F04/K04⁴⁾



NG	A1	A2	А3	A4 (02)	A4 (04)	A5	(K)	(F)
71	11.83	0.51	0.39	0.67	0.61	DIA 4	+0.001	+0.001
	(000.0)	(4.0)	(0, 0)	(4.7)	(45.5)	/~1010	+0.035)	(+0.035)
	(300.6)	(13)	(9.8)	(17)	(15.5)	(Ø101.6	0.033)	(10.033)
90	12.01	0.35	0.43	0.67	0.59	DIA 4	+0.001 0	+0.001 0
	(305)	(9)	(11)	(17)	(15)	(Ø101.6	^{+0.035})	(+0.022) 0
125	13.03	0.39	0.43	0.67	0.65	DIA 4	+0.001 0	+0.001 0
	(330.9)	(10)	(11)	(17)	(16.5)	(Ø101.6	^{+0.025})	(+0.025) 0
NG		A7 ²⁾						
71, 9	0	1/2 in	-13 UN	IC; 0.83 (21) deep)		
125		1/2 in	-13 UN	IC; 0.71 (18) deep)		
		A6						
F02/	K02	DIA 0	.94					
		(ø24)						
F04/	K04	DIA 1	.06					
		(ø27)						

¹⁾ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Thread according to ASME B1.1

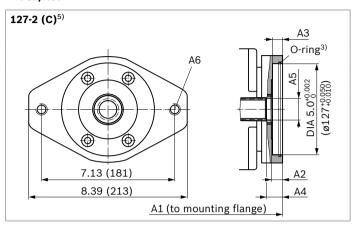
³⁾ O-ring included in the scope of delivery

⁴⁾ The illustration shows the 2-hole version. Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

⁵⁾ For F04/K04 9.7 mm

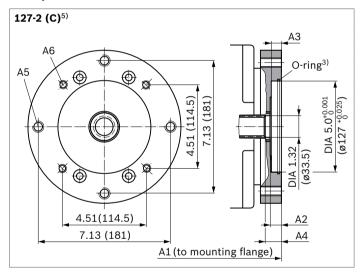
Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
127-2 (C)	1 1/4 in 14T 12/24DP ¹⁾	-	-	•	•	•	•	07
152-2/4 (D)	1 3/4 in 13T 8/16DP ¹⁾	-	-	-	-	-	•	69

▼ F07/K07⁴⁾



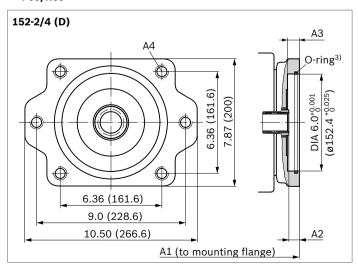
NG	A1	A2	А3	A4	A5	A6 ²⁾
56	10.49	0.59	0.55	0.69	DIA 1.29	5/8 in -11 UNC;
	(266.4)	(15)	(14)	(17.5)	(ø32.7)	0.79 (20) deep
71	11.95	0.59	0.53	0.79	DIA 1.32	5/8 in -11 UNC;
	(303.6)	(15)	(13.5)	(20)	(ø33.5)	0.94 (24) deep

▼ F07/K07⁴⁾



NG	A1	A2	А3	A4		
90	12.17	0.51	0.55	0.81		
	(309)	(13)	(14)	(20.5)		
125	13.22	0.59	0.61	0.89		
	(335.9)	(15)	(15.5)	(22.5)		
NG		A5 ²⁾		A6 ²⁾		
90, 125		5/8 in -1	1 UNC;	1/2 in -13 UNC;		
) deep	0.71 (18) deep		

▼ F69/K69⁶⁾



NG	A1	A2	А3	A4 ²⁾
125	13.54	0.71	0.55	3/4 in -10 UNC; 0.79 (20)
	(343.9)	(18)	(14)	deep

- $_{\rm 1)}$ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to ASME B1.1
- 3) O-ring included in the scope of delivery
- 4) The illustration shows the 4- and the 2-hole version. Please state in plain text whether the 4-hole, the 2-hole horizontal or the 2-hole vertical version is used.
- 5) NG90 to 125 with additional 4-hole-flange (127-4)
- 6) The illustration shows the 4+2-hole version. Please state in plain text whether the 2-hole, the 4-hole or the 4+2-hole vertical version is used.

Overview of mounting options

Through driv	/e ¹⁾		Mounting option – 2. pump					
Flange	Hub for splined shaft	Code	AA4VG/32 NG (shaft)	A10V(S)O/3X NG (shaft)	A10V(S)O/5X NG (shaft)	A11VO/1 NG (shaft)	A10VG NG (shaft)	External gear pump ²⁾
82-2 (A)	5/8 in	F/K01	+	18 (U)	10, 18 (U)	-	_	AZPF NG4 to 22
101-2 (B)	7/8 in	F/K02	-	28 (S) 45 (U)	28 (S) 45 (U)	-	18 (S)	AZPN NG20 to 36 AZPG NG32 to 50
	1 in	F/K04	28 (S)	45 (S)	45 (S) 60, 63, 72 (U)	40 (S)	28 (S) 45 (S)	-
127-2 (C) ³⁾	1 1/4 in	F/K07	40, 56, 71 (S)	71 (S) 100 (U)	60, 63, 71 (S) 85, 100 (U)	60 (S)	63 (S)	-
152-2/4 (D)	1 3/4 in	F/K69	90, 125 (S)	140 (S)	_	95, 130, 145 (S)	-	-

¹⁾ Availability of the individual sizes, see type code on page 3.

²⁾ Bosch Rexroth recommends special versions of the gear pumps. Please contact us.

Combination pumps AA4VG + AA4VG

Total length A

AA4VG	AA4VG 2. Pump ¹	AA4VG 2. Pump ¹⁾				
1st pump	NG28	NG40	NG56	NG71	NG90	NG125
NG28	17.87 (453.8)	_	_	_	_	=
NG40	18.27 (464.1)	18.90 (480.4)	_	_	_	-
NG56	19.13 (485.8)	19.77 (502.1)	22.58 (522.8)	_	_	-
NG71	20.63 (524.0)	21.23 (539.3)	22.05 (560.0)	23.51 (597.2)	_	-
NG90	20.80 (528.4)	21.44 (544.7)	22.26 (565.4)	23.72 (602.6)	24.02 (610.0)	_
NG125	21.82 (554.3)	22.50 (571.6)	23.32 (592.3)	24.78 (629.5)	25.39 (644.9)	26.39 (670.3)

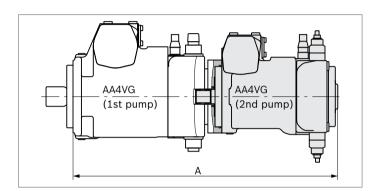
By using combination pumps, it is possible to have independent circuits without the need for splitter gearboxes. When ordering combination pumps, the type designations of the 1st and 2nd pumps must be linked by a "+". Order example:

AA4VG56EP3D1/32R-NAC02F073SP + AA4VG56EP3D1/32R-NSC02F003SP

A tandem pump, with two pumps of equal size, is permissible without additional supports, assuming that the dynamic acceleration does not exceed maximum 10 $g = 322 \text{ ft/s}^2$ (98.1 m/s²).

From size 71 upward, we recommend using the 4-hole mounting flange.

For combination pumps consisting of more than two pumps, the mounting flange must be rated for the permissible moment of inertia, please consult us.



^{1) 2}nd pump without through drive and with boost pump, F00

High-pressure relief valves

The two high-pressure relief valves protect the hydrostatic transmission (pump and motor) from overloading. They limit the maximum pressure in the respective high-pressure line and serve simultaneously as boost valves.

High-pressure relief valves are not working valves and are only suitable for pressure peaks or high rates of pressure change.

Setting ranges

High-pressure relief valve, direct operated (NG28 to 56)	Differential pressure setting $\Delta p_{ ext{HD}}$
Valve setting range 3 , 5	6100 psi (420 bar)
Δp 3600 to 420 psi	5800 psi (400 bar)
(250 to 420 bar) (see type code)	5200 psi (360 bar)
(see type code)	4950 psi (340 bar)
	4650 psi (320 bar)
	4350 psi (300 bar)
	3900 psi (270 bar)
	3600 psi (250 bar)
Valve setting range 4 , 6	3600 psi (250 bar)
Δp 870 to 3600 psi	3350 psi (230 bar)
(100 to 250 bar) (see type code)	2900 psi (200 bar)
(see type code)	2200 psi (150 bar)
	1450 psi (100 bar)

High-pressure relief valve, pilot operated (NG71 to 125)	Differential pressure setting Δp_{HD}
Valve setting range 1	6100 psi (420 bar)
Δp 1450 to 6100 psi	5800 psi (400 bar)
(100 to 420 bar) (see type code)	5200 psi (360 bar)
(see type code)	4950 psi (340 bar)
	4650 psi (320 bar)
	4350 psi (300 bar)
	3900 psi (270 bar)
	3600 psi (250 bar)
	3350 psi (230 bar)
	2900 psi (200 bar)
	2200 psi (150 bar)
	1450 psi (100 bar)

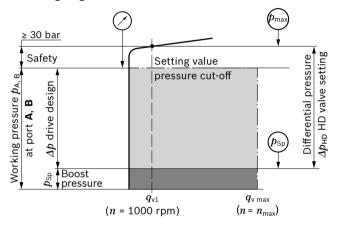
Settings on high-pressure relief valve A and B				
Differential pressure setting	Δp_{HD} = bar			
Cracking pressure of the HD valve (at $q_{ m V1}$)	p _{max} = bar			
$(p_{max} = \Delta p_{HD} + p_{Sp})$				

- ► The valve settings are made at n = 1000 rpm and at $V_{\rm g \ max} \ (q_{\rm v \ 1})$. There may be deviations in the cracking pressures with other operating parameters.
- ► When ordering, state differential pressure setting in plain text.

▼ Example

Working pressure		Boost pressure		Safety		Differential pressure
$p_{A,B}$		p_{Sp}				Δp_{HD}
5800 psi	-	435 psi	+	435 psi	=	5800 psi
(400 bar)		(30 bar)		(30 bar)		(400 bar)

▼ Setting diagram



Bypass function

A connection between the two high-pressure channels **A** and **B** can be established using the bypass valve (e.g. for machine towing).

▶ Towing speed

The maximum towing speed is dependent on the gear ratio in the vehicle and must be calculated by the vehicle manufacturer. The corresponding flow of $q_{\rm v}$ = 7.9 gmp (30 l/min) may not be exceeded.

▶ Towing distance

The vehicle may only be towed out of the immediate danger zone.

For further information on the bypass function, see the instruction manual.

Notice

The bypass function and the pilot-operated high pressure relief valves (size 71 to 125) are not illustrated in the circuit diagrams.

Pressure cut-off

The pressure cut-off is a pressure control which, after reaching the set pressure, adjusts the displacement of the pump back to $V_{\rm g\,min}$.

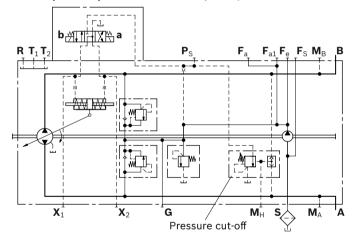
This valve prevents the operation of the high-pressure relief valves when accelerating or decelerating.

The high-pressure relief valves protect against the pressure peaks which occur during fast swiveling of the swashplate and limit the maximum pressure in the system.

The setting range of the pressure cut-off may be anywhere within the entire working pressure range. However, it must be set 435 psi (30 bar) lower than the setting value of the high-pressure relief valves (see setting diagram, page 53).

Please state the setting value of the pressure cut-off in plain text when ordering.

▼ Circuit diagram with pressure cut-off Example: Two-point electric control, EZ1D/EZ2D

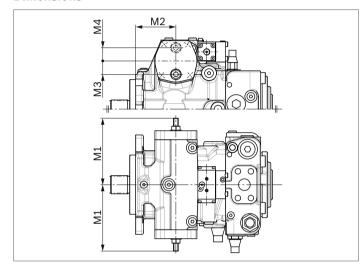


Mechanical stroke limiter

The mechanical stroke limiter is an auxiliary function allowing the maximum displacement of the pump to be steplessly reduced, regardless of the control module used.

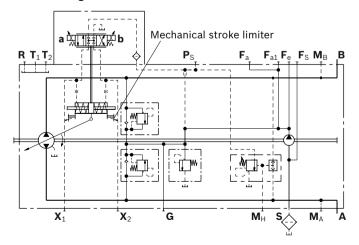
By means of two threaded pins, the stroke of the stroking piston and thus the maximum swivel angle of the pump can be limited.

Dimensions



.5)
.5)

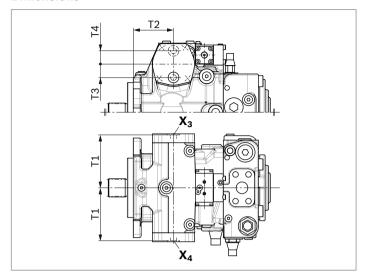
▼ Circuit diagram¹⁾



¹⁾ Size 28 without port F_{a1} and F_{S}

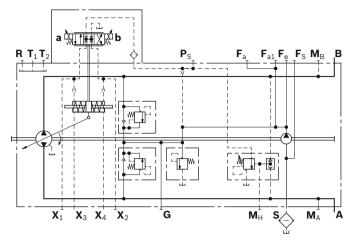
Stroking chamber pressure port X_3 and X_4

Dimensions



NG	T1	T2	T3	T4
56	4.11	1.73	_	0.98
	(104.5)	(44)	_	(25)
71	4.47	3.40	1.10	_
	(113.5)	(86.3)	(28)	_
90	4.39	3.77	-	1.18
	(111.5)	(95.7)	_	(30)
125	5.35	4.11	1.34	_
	(136)	(104.5)	(34)	_

▼ Circuit diagram¹⁾



Ports		Standard ²⁾	Size	p_{max} [psi (bar)] $^{3)}$	State ⁴⁾
X ₃ , X ₄	Stroking chamber pressure port	ISO 11926	7/16in-20 UNF-2B; 0.47 (12) deep	580 (40)	X

¹⁾ Size 28 without port \boldsymbol{F}_{a1} and \boldsymbol{F}_{S}

 $_{\mbox{\scriptsize 2)}}$ The countersink can be deeper than as specified in the standard.

³⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

⁴⁾ X = Plugged (in normal operation)

Filtration in the boost pump suction line

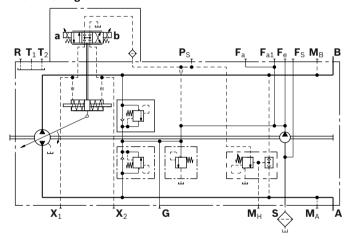
Version S

Filter version	Suction filter without bypass
Recommendation	With contamination indicator
Recommended flow resistance at fil	ter element
At $v = 140 \text{ SUS } (30 \text{ mm}^2/\text{s}), n = n_{\text{max}}$	$\Delta p \le 1.5 \text{ psi (0.1 bar)}$
At $v = 4600 \text{ SUS } (1000 \text{ mm}^2/\text{s}),$	Δp ≤ 4.5 psi (0.3 bar)
$n = n_{\text{max}}$	
Pressure at suction port S	
Continuous $p_{\text{S min}}$	≥ 12 psi (0.8 bar) absolute
$(v \le 140 \text{ SUS } (30 \text{ mm}^2/\text{s}))$	
Short-term, at a cold start	≥ 7.5 psi (0.5 bar) absolute
(t < 3 min)	
Maximum pressure $p_{\text{S max}}$	≤ 75 psi (5 bar) absolute

Use of version S is preferred.

The suction filter is not included in the scope of delivery.

▼ Circuit diagram



Filtration in the boost pump pressure line

Version D Ports for external boost circuit filtration

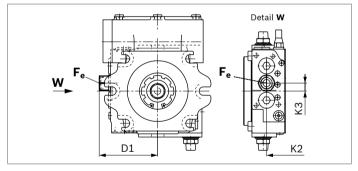
Ports					
Boost pressure inlet	Port F _a				
Boost pressure outlet	Port F _e				
Filter version	Boost pressure filter without bypass				
Recommendation	With contamination indicator				
Filter arrangement	Separate in the pressure line (inline filter)				
Permissible flow resistance at filter element ¹⁾					
At ν = 140 SUS (30 mm ² /s)	Δp ≤ 15 psi (1 bar)				
For cold start	Δp ≤ 45 psi (3 bar)				
	*				

Notice

- ► Filters with a bypass **not recommended**, (exception DG, see below). Please contact us for applications with a bypass.
- On versions with DG control (with pilot pressure not from a boost circuit), a filter with a bypass and with a contamination indicator must be used.

The boost pressure filter is not included in the scope of delivery.

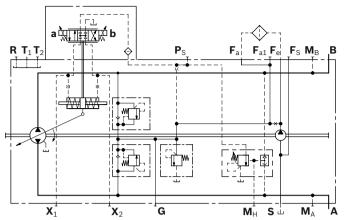
▼ Dimensions



NG	D1 ¹⁾	F _e ²⁾
28	See page 23	3/4 in-16 UNF-2B; 0.59 (15) deep
40	4.49	3/4 in-16 UNF-2B; 0.59 (15) deep
	(113)	
56	4.57	3/4 in-16 UNF-2B; 0.59 (15) deep
	(116)	
71	5.27	1 1/16 in-12 UN; 0.63 (16) deep
	(133.9)	
90	5.04	1 1/16 in-12 UN; 0.63 (16) deep
	(128)	
125	5.83	1 5/16 in-12 UN-2B; 0.63 (16) deep
	(148)	

 $[\]overline{}_{1)}$ Valid for entire speed range n_{\min} to n_{\max}

▼ Circuit diagram



Version K

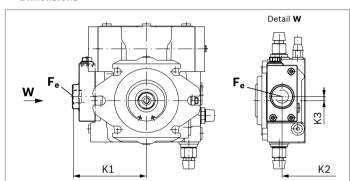
Mounted cold start valve and ports for external boost circuit filtration

Filtration as version D, but with additional cold start valve. The port plate is equipped with a cold start valve to protect the pump against damage. The valve opens at flow resistance of $\Delta p \ge 6$ bar.

Ports	
Boost pressure inlet	Port F _a
Boost pressure outlet	Port F _e
Filter version	Boost pressure filter without bypass
Recommendation	With contamination indicator
Filter arrangement	Separate in the pressure line (inline filter)
Permissible flow resis	tance at filter element ¹⁾
At $v = 30 \text{ mm}^2/\text{s}$	$\Delta p \le 1$ bar
For cold start	<i>Δp</i> ≤ 3 bar

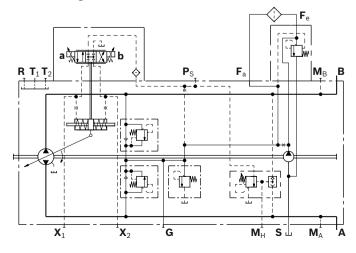
The boost pressure filter is not included in the scope of delivery.

▼ Dimensions



NG	K1	K2	К3	F _e ²⁾
40	4.82	7.82	0	3/4 in-16 UNF-2B;
	(122.5)	(198.7)	(0)	0.59 (15) deep
56	4.94	8.48	0	3/4 in-16 UNF-2B;
	(125.5)	(215.4)	(0)	0.59 (15) deep

▼ Circuit diagram



The countersink may be deeper than specified in the standard.

¹⁾ Valid for entire speed range n_{\min} - n_{\max}

²⁾ Thread according to ISO 11926;

³⁾ To protect the filter element against electrostatic charge, the hydraulic fluid must have a minimum conductivity of 300 pS/m on versions with attachment filter F, P and B. Please contact us if this value cannot be observed.

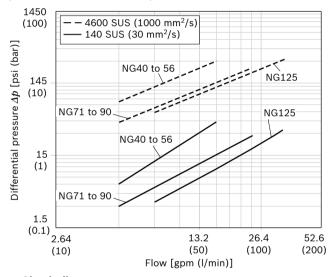
Version F¹⁾
Attachment filter with cold start valve

Filter version	Attachment filter without bypass
Recommendation	Version with contamination indicator, see P, B (differential pressure Δp = 75 psi (5 bar))
Filter grade (absolute)	20 μm
Filter material	Glass fiber
Pressure rating	1450 psi (100 bar)
Filter arrangement	Mounted on pump

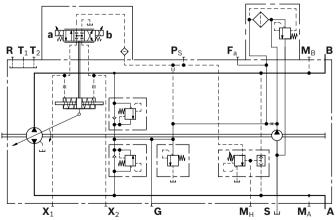
The attachment filter is equipped with a cold start valve and thereby protects the pump from damage. The valve opens at flow resistance of $\Delta p \ge 87$ psi (6 bar).

▼ Filter characteristics

Differential pressure/flow characteristics to ISO 3968 (valid for clean filter element).



▼ Circuit diagram



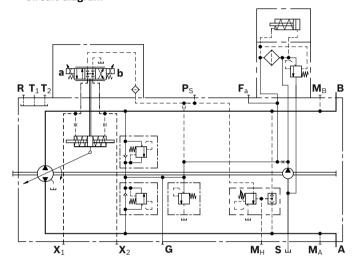
¹⁾ To protect the filter element against electrostatic charge buildup, the hydraulic fluid must have a minimum conductivity of 300 pS/m on versions with attachment filter F, P and B. Please contact us if this value cannot be observed.

Version P¹⁾ Attachment filter with cold start valve and visual contamination indicator

Filtration similar to version F, however with additional visual contamination indicator.

Technical data				
Display type	Green/red window			
Differential pressure	Δp = 75 psi (5 bar)			
(switching pressure)				

▼ Circuit diagram



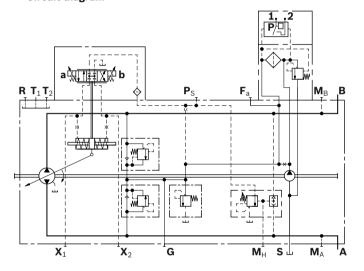
Version B1)

Attachment filter with cold start valve and electric contamination indicator

Filtration similar to version F, however with additional electric contamination indicator.

Technical data		
Display type	Electrical	
Connector version (mating connector, see page 62)	DEUTSCH DT04	4-2P-EP04
Differential pressure (switching pressure)	Δp = 75 psi (5	bar)
Maximum switching capacity	12 V DC	24 W
	24 V DC	48 W
Type of protection IP67	DIN EN 60529	

▼ Circuit diagram



External boost pressure supply

Version E

This variation should be used in versions without integrated boost pump $(\mathbf{N} \text{ and } \mathbf{K})$.

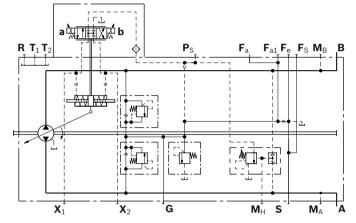
Port **S** is plugged.

The boost pressure supply comes from port \mathbf{F}_a .

The filter should be installed separately on port \mathbf{F}_a before the boost pressure supply.

To ensure the functional reliability, maintain the required cleanliness level for the boost fluid fed in at port \mathbf{F}_a (see page 6).

▼ Circuit diagram

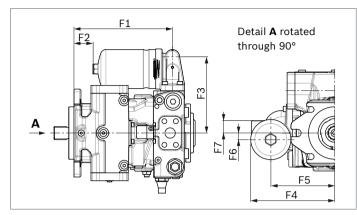


¹⁾ To protect the filter element against electrostatic charge buildup, the hydraulic fluid must have a minimum conductivity of 300 pS/m on versions with attachment filter F, P and B. Please contact us if this value cannot be observed.

Dimensions with filter fitted

▼ Version F

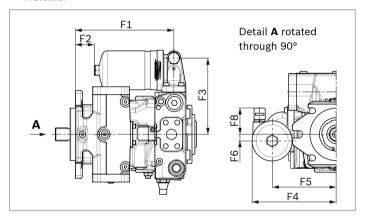
Attachment filter with cold start valve



NG	F1	F2	F3	F4	F5	F6	F7	F8
40	7.94	1.88	6.30	6.89	5.31	0	1.65	3.09
	(201.7)	(47.7)	(160)	(175)	(135)	(0)	(42)	(78.5)
56	8.60	2.54	6.42	7.01	5.43	0	1.65	3.09
	(218.4)	(64.4)	(163)	(178)	(138)	(0)	(42)	(78.5)
71	9.41	1.83	7.28	8.01	6.10	0.63	1.14	2.58
	(239)	(46.5)	(185)	(203.5)	(155)	(16)	(29)	(65.5)
90	9.78	2.20	7.05	7.78	5.87	0	1.77	3.21
	(248.5)	(56)	(179)	(197.5)	(149)	(0)	(45)	(81.5)
125	9.29	2.34	7.91	8.64	6.73	0	2.09	3.52
	(235.9)	(59.4)	(201)	(219.5)	(171)	(0)	(53)	(89.5)

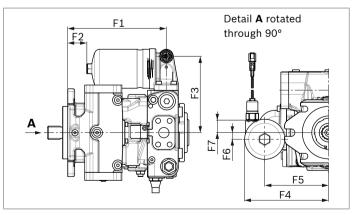
▼ Version P

Attachment filter with cold start valve and visual contamination indicator



▼ Version B

Attachment filter with cold start valve and electric contamination indicator



Swivel angle sensor

The swivel angle sensor is used to detect the swivel angle of axial piston units and thus the displacement using a Hall-effect based sensor IC. The determined measurement value is converted into an analog signal.

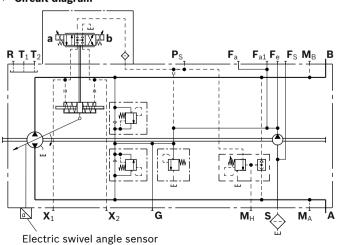
Please contact us if the swivel angle sensor is used for control.

Characteristics	
Supply voltage U_{b}	10 to 30 V DC
Output voltage U_{a}	0.5 V 2.5 V 4.5 V
	$(V_{\text{g max}})$ $(V_{\text{g 0}})$ $(V_{\text{g max}})$
Reverse polarity protection	Short-circuit resistant
EMC resistance	Details on request
Operating temperature range	-40 °F to +239 °F
	(-40 °C to +115 °C)
Vibration resistance,	10 g / 5 to 2000 Hz
sinusoidal vibration EN 60068-2-6	
Shock resistance:	25 g
continuous shock IEC 68-2-29	
Salt spray resistance (DIN 50 021-SS)	96 h
Type of protection with installed	IP67 - DIN/EN 60529
mating connector	IP69K - DIN 40050-9
Housing material	Plastic
Connector version	AMP Super Seal 1.5

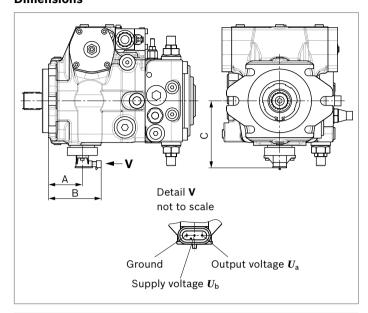
Output voltage

Direction	Flow	Working	Output v	Output voltage	
of rotation	n direction pressure		at $V_{ m g~0}$	at $V_{ m g\ max}$	
clockwise	A to B	M _B	2.5 V	4.5 V	
	B to A	M _A	2.5 V	0.5 V	
counter-	B to A	M _A	2.5 V	4.5 V	
clockwise	A to B	M _B	2.5 V	0.5 V	

▼ Circuit diagram



Dimensions



NG	Α	В	С
56	2.38	3.84	5.06
	(60.5)	(97.5)	(128.5)

Mating connector AMP Superseal 1.5; 3-pin

Consisting of	AMP No.
1 socket housing, 3-pin	282087-1
3 single-wire seals, yellow	281934-2
3 socket contacts 1.8 - 3.3 mm	183025-1

The mating connector is not included in the scope of delivery. This can be supplied by Bosch Rexroth on request (material number R902602132).

Notice

It is not possible to retrofit existing units with a swivel angle sensor.

Connector for solenoids

DEUTSCH DT04-2P-EP04

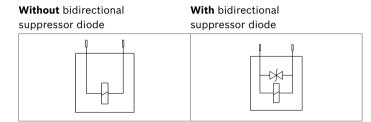
- ► **P**: Molded, 2-pin, without bidirectional suppressor diode (standard).
- ▶ **Q**: Molded, 2-pin, with bidirectional suppressor diode (only for switching solenoids on control module EZ and DA)

The following type of protection ensues with the installed mating connector:

- ▶ IP67 (DIN/EN 60529) and
- ► IP69K (DIN 40050-9)

The protection circuit with bidirectional suppressor diode is needed to limit overvoltages. Overvoltages are caused by switching off the current with switches, relay contacts or by disconnecting the mating connector while voltage is applied.

▼ Switching symbol



▼ Mating connector DEUTSCH DT06-2S-EP04

Consisting of	DT designation
1 housing	DT06-2S-EP04
1 wedge	W2S
2 sockets	0462-201-16141

The mating connector is not included in the scope of delivery. This can be supplied by Bosch Rexroth on request (material number R902601804).

Notice

- ► If necessary, you can change the position of the connector by turning the solenoid.
- ▶ The procedure is defined in the instruction manual.

Rotary inch valve

Any reduction of the pilot pressure possible, independently of the drive speed, through mechanical actuation of the position lever. Maximum angle of rotation 90°, lever position: any. The valve is arranged separately from the pump and is connected to the pump by a hydraulic control line via port \mathbf{P}_{S} (maximum line length: approx. 6.5 ft (2 m)).

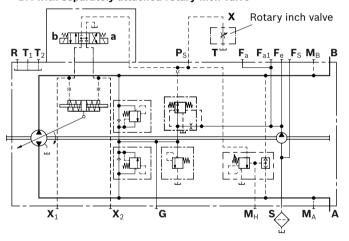
The rotary inch valve must be ordered separately.

NG	Material number	Direction of actuation of the position lever	Throttle cross-section DIA (Ø)
28, 40, 56,	R902048738	Clockwise	0.18 (4.6)
71, 90	R902048739	Counter-clockwise	0.18 (4.6)

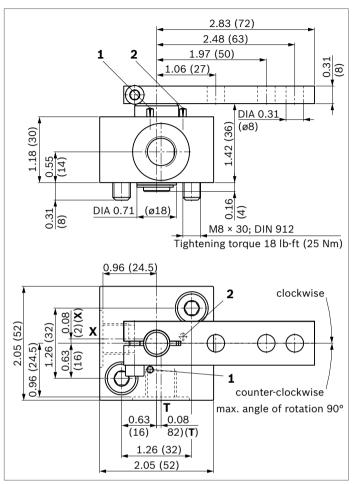
Notice

The rotary inch valve can be used regardless of the control module.

▼ Circuit diagram: Hydraulic control, speed-related, DA with separately attached rotary inch valve



Dimensions



Notice

Limitation ${\bf 1}$ and ${\bf 2}$ are function stops for inching. They are not to be used as a mechanical limitation within the system. We recommend limiting the angle of rotation to 85° within the system.

Ports		Standard ¹⁾	Size	p _{max} [psi (bar)] ²⁾	State ³⁾
х	Pilot pressure port	ISO 11926	9/16 in -18 UNF-2B; 0.51 (13 deep)	580 (40)	0
Т	Drain port	ISO 11926	9/16 in -18 UNF-2; 0.51 (13 deep)	45 (3)	0

 $[\]scriptstyle \mbox{\scriptsize 1)}$ The countersink can be deeper than as specified in the standard.

²⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

³⁾ O = Must be connected (plugged on delivery)

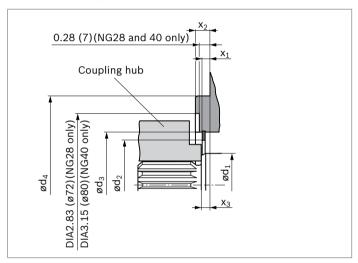
Installation dimensions for coupling assembly

To ensure that rotating components (coupling hub) and fixed components (housing, snap ring) do not come into contact with each other, the installation conditions described here must be observed. This depends on the pump size and the splined shaft.

SAE splined shaft (spline according to ANSI B92.1a)

Splined shaft S or T

The outer diameter of the coupling hub must be smaller than the inner diameter of the snap ring (dimension d_2) in the area near the drive shaft collar (dimension $x_2 - x_3$). Observe diameter of relief on sizes 28 and 40.



NG	$ød_1$	ød _{2 min}	ød ₃	ød ₄	x ₁	X ₂	X ₃	x ₄
28	1.38	1.71	2.17±0.004	4.00	0.13 +0.008	0.37 _{-0.02}	0.31 +0.035 -0.024	$0.39^{+0.035}_{-0.024}$
	(35)	(43.4)	(55±0.1)	(101.6)	(3.3 +0.2)	(9.5 _{-0.5})	(8 ^{+0.9} _{-0.6})	(10 ^{+0.9} _{-0.6})
40	1.57	2.02	2.48±0.004	5.00	0.17 +0.008	0.5 -0.02	0.31 +0.035 -0.024	0.39 ^{+0.035} _{-0.024}
	(40)	(51.4)	(63±0.1)	(127)	(4.3 +0.2)	(12.7 _{-0.5})	(8 +0.9)	(10 ^{+0.9} _{-0.6})
56	1.57	2.14	2.68±0.004	5.00	0.28 +0.008	0.5 -0.02	0.31 +0.035 -0.024	0.39 ^{+0.035} _{-0.024}
	(40)	(54.4)	(68±0.1)	(127)	(7.0 +0.2)	(12.7 _{-0.5})	(8 ^{+0.9} _{-0.6})	(10 ^{+0.9} _{-0.6})
71	1.77	2.62	3.19±0.004	5.00	0.28 +0.008	0.5 -0.02	0.31 +0.035 -0.024	0.39 ^{+0.035} _{-0.024}
	(45)	(66.5)	(81±0.1)	(127)	(7.0 ^{+0.2})	(12.7 _{-0.5})	(8 +0.9)	(10 ^{+0.9} _{-0.6})
90	1.97	2.62	3.19±0.004	6.00	0.27 +0.008	0.5 -0.02	0.31 +0.035 -0.024	0.39 ^{+0.035} _{-0.024}
	(50)	(66.5)	(81±0.1)	(152.4)	(6.8 ^{+0.2})	(12.7 _{-0.5})	(8 +0.9)	(10 ^{+0.9} _{-0.6})
125	2.17	3.00	3.58±0.004	6.00	0.28 +0.008	0.5_0.02	0.31 +0.035 -0.024	0.39 ^{+0.035} _{-0.024}
	(55)	(76.3)	(91±0.1)	(152.4)	(7.0 +0.2)	(12.7 _{-0.5})	(8 +0.9)	(10 ^{+0.9} _{-0.6})

Installation instructions

General

air bled during commissioning and operation. This must also be observed following a longer standstill as the axial piston unit may empty via the hydraulic lines. Particularly in the installation position "drive shaft upwards", filling and air bleeding must be carried out completely as there is, for example, a danger of dry running. The leakage in the housing area must be directed to the reservoir via the highest drain port (T_1, T_2) . For combination pumps, the leakage must be drained off at each pump. If a shared drain line is used for several units, make sure that the respective case pressure is not exceeded. The shared drain line must be dimensioned to ensure that the maximum permissible case pressure of all connected units is not exceeded in any operating conditions, specifically on cold start. If this is not possible, separate drain lines must be laid if necessary.

The axial piston unit must be filled with hydraulic fluid and

To achieve favorable noise values, decouple all connecting lines using elastic elements and avoid above-reservoir installation

Under all operating conditions, the suction line and drain line must flow into the reservoir below the minimum fluid level. The permissible suction height h_S results from the overall loss of pressure. However, it must not be higher than $h_{S max} = 31.50$ in (800 mm).

The suction pressure at port **S** must also not fall below the minimum value of 12 psi (0.8 bar) absolute during operation (cold start 7.5 psi (0.5 bar) absolute).

Installation position

See the following examples 1 to 12.

Further installation positions are available upon request. Recommended installation position: 1 and 2.

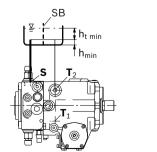
Notice

- Size 71 to 125 For installation position "drive shaft upward", an R₁ port is needed (special version).
- If filling the stroking chambers via X_1 to X_4 is not possible in the final installation position, then this must take place before installation, e. g. in installation position 2.
- To prevent unexpected actuation and damage, the stroking chambers must be air bled via the ports X₁,
 X₂, or X₃, X₄ depending on the installation position.
- ► In certain installation positions, an influence on the control characteristic can be expected. Gravity, dead weight and case pressure can cause minor shifts in control characteristic curves and changes in response time

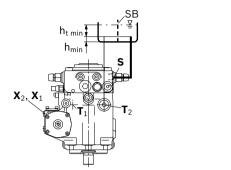
Below-reservoir installation (standard)

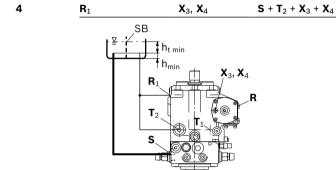
Below-reservoir installation means that the axial piston unit is installed outside of the reservoir and below the minimum fluid level of the reservoir.

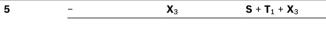
Installation position	Air bleeding the housing	Air bleeding the stroking chamber	Filling
1	R	$\mathbf{X}_1, \mathbf{X}_2$	$S + T_1 + X_1 + X_2$
	h _{t min}	SB T ₁	
2		_	S + T ₂
	†	SB - The min	

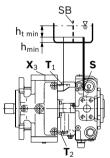


Installation position	Air bleeding the housing	Air bleeding the stroking chamber	Filling
3	_	X ₁ , X ₂	S + T ₂ + X ₁ + X ₂
		CD	'

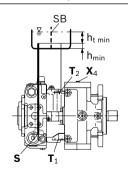








6 - X_4 S + T_2 + X_4

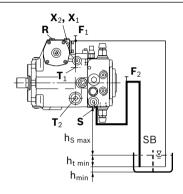


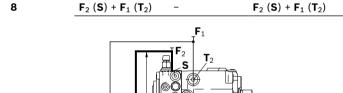
Above-reservoir installation

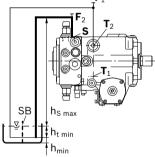
Above-reservoir installation means that the axial piston unit is installed above the minimum fluid level of the reservoir. Observe the maximum permissible suction height $h_{\text{S max}}$ = 31.50 in (800 mm).

Recommendation for installation position 10 (drive shaft upward): A check valve in the drain line (cracking pressure 7.5 psi (0.5 bar)) can prevent the housing area from draining.

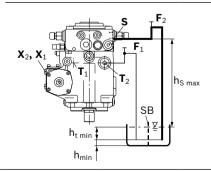
Installation position	Air bleeding the housing	Air bleeding the stroking chamber	Filling
7	E D	v v	F . F . V . V







9 $F_2(S) + F_1(T_2)$ X_1, X_2 $F_2(S) + F_1(T_2)$ $+ X_1 + X_2$



Installation position	Air bleeding the housing	Air bleeding the stroking chamber	Filling
10	F ₂ + R ₁	X ₃ , X ₄	F ₁ + F ₂ + X ₃ + X ₄
	F ₂ January Sparage	F ₁ X ₃ , T ₂ T ₁ S S h _{S max} h _{t min}	R
11	$F_2(S) + F_1(T_1)$	X ₃	F_2 (S) + F_1 (T_1) + X_3
	X ₃ T ₁	F ₁ S F ₂ h _{t min} h _{min}	3
12	\mathbf{F}_2 (S) + \mathbf{F}_1 (\mathbf{T}_2)	X ₄	\mathbf{F}_2 (S) + \mathbf{F}_1 (\mathbf{T}_2) + \mathbf{X}_2
	SB F2	F ₁ T ₂ X ₄ S max S T ₁	

h_{min}

Key	
F ₁ , F ₂	Filling / air bleeding
R	Air bleed port
R_1	Air bleed port (special version)
S	Suction port
T ₁ , T ₂	Drain port
$\mathbf{X}_1, \mathbf{X}_2$	Control pressure port
X ₃ , X ₄	Stroking chamber pressure port
SB	Baffle (baffle plate)
h _{t min}	Minimum required immersion depth 7.87 in (200 mm)
h _{min}	Minimum required distance to reservoir bottom 3.94 in
	(100 mm)
h _{S max}	Maximum permissible suction height 31.5 in (800 mm)

Notice

Ports ${\bf F_1}$ and ${\bf F_2}$ are part of the external piping and must be provided on the customer side to make filling and air bleeding easier.

Project planning notes

- ▶ The pump AA4VG is designed to be used in closed circuit.
- ► The project planning, installation and commissioning of the axial piston unit requires the involvement of qualified skilled personnel.
- ▶ Before using the axial piston unit, please read the corresponding instruction manual completely and thoroughly. If necessary, these can be requested from Bosch Rexroth.
- ► Before finalizing your design, please request a binding installation drawing.
- The specified data and notes contained herein must be observed.
- ► Depending on the operating conditions of the axial piston unit (working pressure, fluid temperature), the characteristic curve may shift.
- ▶ Preservation: Our axial piston units are supplied as standard with preservative protection for a maximum of 12 months. If longer preservative protection is required (maximum 24 months), please specify this in plain text when placing your order. The preservation periods apply under optimal storage conditions, details of which can be found in the data sheet 90312 or the instruction manual.
- ▶ Not all versions of the product are approved for use in a safety function according to ISO 13849. Please consult the responsible contact person at Bosch Rexroth if you require reliability parameters (e.g. MTTF_D) for functional safety.
- ▶ Depending on the type of control used, electromagnetic effects can be produced when using solenoids. When a direct current is applied, solenoids do not cause electromagnetic interference nor is their operation impaired by electromagnetic interference. Other behavior can result when a modulated direct current
 - (e.g. PWM signal) is applied. Potential electromagnetic interference for persons (e.g. persons with a pacemaker) and other components must be tested by the machine manufacturer.
- ► The pressure cut-off is not a safeguard against pressure overload. Be sure to add a pressure relief valve to the hydraulic system.
- Please note the details regarding the tightening torques of port threads and other threaded joints in the instruction manual.

- ► Working ports:
 - The ports and fastening threads are designed for the specified maximum pressure. The machine or system manufacturer must ensure that the connecting elements and lines correspond to the specified application conditions (pressure, flow, hydraulic fluid, temperature) with the necessary safety factors.
 - The working ports and function ports are only intended to accommodate hydraulic lines.

Safety instructions

- During and shortly after operation, there is a risk of getting burnt on the axial piston unit and especially on the solenoids. Take appropriate safety measures (e.g. by wearing protective clothing).
- ▶ Moving parts in control equipment (e.g. valve spools) can, under certain circumstances get stuck in position as a result of contamination (e.g. impure hydraulic fluid, abrasion, or residual dirt from components). As a result, the hydraulic fluid flow and the build-up of torque in the axial piston unit can no longer respond correctly to the operator's specifications. Even the use of various filter elements (external or internal flow filtration) will not rule out a fault but merely reduce the risk.

 The machine/system manufacturer must test whether remedial measures are needed on the machine for the application concerned in order to set the consumer being driven to a safe position (e.g. safe stop) and if necessary to ensure it is properly implemented.
- ► Moving parts in high-pressure relief valves may in certain circumstances become stuck in an undefined position due to contamination (e.g. impure hydraulic fluid). This can result in restriction or loss of the load holding function in lifting winches.
 - The machine/system manufacturer must check whether additional measures are required on the machine for the relevant application in order to keep the load in a safe position and ensure they are properly implemented.

Bosch Rexroth Corporation

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